

# Linear Regression

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# Chapter 1

## Installation

### 1.1 UNIX

If you are unfamiliar with UNIX, see your system administrator or system documentation for information on the system commands referred to below. The device names given are probably correct for your system.

#### 1.1.1 Download

1. Copy the `.tar.gz` file to `/tmp`.

2. Unzip the file.

```
gunzip appxxx.tar.gz
```

3. `cd` to the **GAUSS** or **GAUSS Engine** installation directory. We are assuming `/usr/local/gauss` in this case.

```
cd /usr/local/gauss
```

4. Untar the file.

```
tar xvf /tmp/appxxx.tar
```

#### 1.1.2 Floppy

1. Make a temporary directory.

```
mkdir /tmp/workdir
```

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2. `cd` to the temporary directory.

```
cd /tmp/workdir
```

3. Use `tar` to extract the files.

```
tar xvf device_name
```

If this software came on diskettes, repeat the `tar` command for each diskette.

4. Read the README file.

```
more README
```

5. Run the `install.sh` script in the work directory.

```
./install.sh
```

The directory the files are install to should be the same as the install directory of **GAUSS** or the **GAUSS Engine**.

6. Remove the temporary directory (optional).

The following device names are suggestions. See your system administrator. If you are using Solaris 2.x, see Section 1.1.3.

Operating System	3.5-inch diskette	1/4-inch tape	DAT tape
Solaris 1.x SPARC	/dev/rfd0	/dev/rst8	
Solaris 2.x SPARC	/dev/rfd0a (vol. mgt. off)	/dev/rst12	/dev/rmt/11
Solaris 2.x SPARC	/vol/dev/aliases/floppy0	/dev/rst12	/dev/rmt/11
Solaris 2.x x86	/dev/rfd0c (vol. mgt. off)		/dev/rmt/11
Solaris 2.x x86	/vol/dev/aliases/floppy0		/dev/rmt/11
HP-UX	/dev/rfloppy/c20Ad1s0		/dev/rmt/0m
IBM AIX	/dev/rfd0	/dev/rmt.0	
SGI IRIX	/dev/rdisk/fds0d2.3.5hi		

### 1.1.3 Solaris 2.x Volume Management

If Solaris 2.x volume management is running, insert the floppy disk and type

```
volcheck
```

to signal the system to mount the floppy.

The floppy device names for Solaris 2.x change when the volume manager is turned off and on. To turn off volume management, become the superuser and type

```
/etc/init.d/volmgt off
```

To turn on volume management, become the superuser and type

```
/etc/init.d/volmgt on
```

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### 1.2 Windows/NT/2000

#### 1.2.1 Download

Unzip the .zip file into the **GAUSS** or **GAUSS Engine** installation directory.

#### 1.2.2 Floppy

1. Place the diskette in a floppy drive.
2. Call up a DOS window
3. In the DOS window log onto the root directory of the diskette drive. For example:

```
A:<enter>
cd\<enter>
```

4. Type: **ginstall** *source\_drive* *target\_path*

*source\_drive*      Drive containing files to install  
with colon included

For example: **A:**

*target\_path*      Main drive and subdirectory to install  
to without a final \

For example: **C:\GAUSS**

A directory structure will be created if it does not already exist and the files will be copied over.

<i>target_path</i> \src	source code files
<i>target_path</i> \lib	library files
<i>target_path</i> \examples	example files

### 1.3 Differences Between the UNIX and Windows/NT/2000 Versions

- If the functions can be controlled during execution by entering keystrokes from the keyboard, it may be necessary to press *Enter* after the keystroke in the UNIX version.

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- On the Intel math coprocessors used by the Windows/NT/2000 machines, intermediate calculations have 80-bit precision, while on the current UNIX machines, all calculations are in 64-bit precision. For this reason, **GAUSS** programs executed under UNIX may produce slightly different results, due to differences in roundoff, from those executed under Windows/NT/2000.



## Chapter 2

# Linear Regression

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The *LINEAR REGRESSION* module is a set of procedures for the estimation of single equation and simultaneous equation models. Single equation models are estimated using *Ordinary Least Squares*. Systems of equations can be estimated using *Two-Stage Least Squares*, *Three-Stage Least Squares*, or *Seemingly Unrelated Regression*.

The core of this module consists of the following procedures:

<b>L2SLS</b>	Linear Two-Stage Least Squares Regression
<b>L3SLS</b>	Linear Three-Stage Least Squares Regression
<b>LREG</b>	Linear Regression by Ordinary Least Squares
<b>LSUR</b>	Linear Seemingly Unrelated Regression

In addition to these estimation procedures, a procedure **LRTEST** is provided for linear hypothesis testing of any of the above regression models.

Special features of the *LINEAR REGRESSION* module include:

- Handles arbitrarily large data sets with multiple variables.
- Performs multiple linear hypothesis testing easily.

## 2. LINEAR REGRESSION

- Estimates regressions with linear restrictions.
- All regression procedures may operate on a specified range of observations.
- Performs iteratively re-weighted *Three-Stage Least Squares* and *Seemingly Unrelated Regression*.

This chapter begins with some general aspects of the use of the *LINEAR REGRESSION* module. The second chapter provides additional topics covering the application of the procedures. Comprehensive details of each estimation procedure are provided in the last chapter.

### 2.0.1 README Files

The file `README.lr` contains any last minute information on this module. Please read it carefully before using the procedures in this module.

### 2.0.2 Version Number

The version number is stored in a global variable `_lr_ver`, which is a  $3 \times 1$  matrix containing the major version, minor version, and revision number in that order.

If you call for technical support, you will be asked for the version number of your copy of this module.

## 2.1 Getting Started Right Away

There are four essential parts to any estimation procedure in this module. These must be specified in any programs that call these estimation procedures.

### 1. Header:

The header consists of two statements. A **LIBRARY** statement which activates the LR library and a call to **LRSET** which resets the global variables to the default state. These two statements are specified at the top of the command file and should look something like this:

```
library lr, pgraph; /* ACTIVATE THE LR AND PGRAPH LIBRARIES. */
lrset;              /* RESET THE LR GLOBAL VARIABLES.      */
```

In the example above, the PGRAPH library is necessary if you intend to use the Publication Quality Graphics.

## 2. LINEAR REGRESSION

### 2. Data Setup:

Next, the user must specify the data to be passed to the procedures. For example, the format for **LREG** is:

```
Q = LREG(dataset,dv,iv,restrict);
```

Here is an example:

```
dataset = "translog"; /* FILE NAME OF THE DATA SET.      */
dv = { y1 };          /* SPECIFY DEPENDENT VARIABLE.    */
iv = { const,x1,x2 }; /* SPECIFY INDEPENDENT VARIABLES. */
```

### 3. Specify Options:

Options are controlled by setting the corresponding global variables. Following the above example, you may want to analyze the data with both *influence* and *collinearity* diagnostics. This can be accomplished by specifying the following two statements:

```
_lregres = "residual";
_lregcol = 1;
```

### 4. Calling the Procedure:

Each estimation procedure can print results to the screen and send output to the specified output file and/or return a global output vector to memory. If all you need is the printed results, you can call the procedure as follows:

```
call lreg(dataset,dv,iv,0);
```

If you want information returned to memory, you must assign the result to a matrix.

```
Q = lreg(dataset,dv,iv,0);
```

The result,  $Q$ , is a packed vector, which stores all the return statistics in an efficient manner. The contents of the output vector for each function are listed in the reference section. The **VREAD** command is used to read packed vectors. The **LRFETCH** procedure, in this *LINEAR REGRESSION* module retrieves important elements of the  $Q$  vector.

## 2.2 Data Transformation

It is assumed that the data set for analysis is ready before you call these procedures. If data transformations are required, you may use the **DATALOOP** in **GAUSS**. A data loop allows selection of observations, transformation of variables, selection of variables, deletion of missing values, etc. Several examples of data transformations can be found in the next chapter. For more details on **DATALOOP**, see the **GAUSS** manual.

## 2.3 GAUSS Data Sets

**GAUSS** data sets are binary files that can be created by using the **GAUSS** utility **ATOG**, see the *UTILITIES* section of the **GAUSS SYSTEM AND GRAPHICS MANUAL**. Data sets can also be created using the **CREATE** or **SAVED** commands. See the **GAUSS COMMAND REFERENCE**. You should think of the file as storing information in rows and columns; each row contains an observation, and each column contains a variable. For more information on data sets, see the *FILE I/O* section of the **GAUSS SYSTEM AND GRAPHICS MANUAL**.

### 2.3.1 The Upper/Lower Case Convention for Distinguishing Character and Numeric Data

To distinguish numeric variables from character variables in **GAUSS** data sets, **GAUSS** recognizes an “upper case/lower case” convention: if the variable name is upper case, the variable is assumed to be numeric. If it is lower case, the variable is assumed to be character. **ATOG** implements this convention automatically when you use the **\$** and **#** operators to toggle between character and numeric variable names listed in the **INVAR** statement.

When creating a data set using the **SAVED** command, this convention can be established as follows:

```
data = { M 32  21500,
         F 27  36000,
         F 28  19500,
         M 25  32000 };
dataset = "mydata";
vnames = { "sex" AGE PAY };
call saved(data,dataset,vnames);
```

It is necessary to put “sex” into quotes in order to prevent it from being forced to upper case.

The procedure **GETNAME** can be used to retrieve the variable names:

```
print $getname("mydata");
```

The names are:

```
sex
AGE
PAY
```

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When you are selecting data using **DATALOOP**, the selection is *case-insensitive*. That is:

```
keep AGE, PAY, SEX;

keep age PAY sex;
```

will both perform the same selection. Only when you are writing or creating a data set (as the above example using **SAVED** does) is the case of the variable name important.

By default, this convention will be observed by all of the application modules to which it applies. That is, if you pass in a data set, the applications will use the case of the variable names in the data set to determine whether the variables are numeric or character.

### 2.3.2 Creating a Data Set

First, you need to know the format of your data file. If the data file is in either a spreadsheet or database format, creating a data set will be easy, since all spreadsheet and database programs have some built-in mechanism allowing them to be saved as an ASCII or text file. Users should consult those program manuals on how to convert data into ASCII format.

If you have data in another format, there are some useful data utility programs such as DBMS/COPY or Stat/Transfer which can transfer data directly from various formats into **GAUSS** format.

If you convert a spreadsheet into an ASCII file, you must be careful to remove the column and row labels from the file. The labels can be incorrectly interpreted as data. You can use a text editor to remove them.

To make it easier to edit the ASCII file later, you should reduce the width of the columns of your spreadsheet to the minimum possible for the precision of your data before converting into ASCII. There are two reasons for this. First, it is easy to scroll across a wide worksheet (i.e., wider than the screen) when in a spreadsheet program, but it is not easy to do or sometimes impossible with a screen editor. Secondly, some spreadsheet programs cannot create ASCII files wider than 256 columns.

Here are some examples:

1. You have a small data file converted from Lotus 1-2-3 that is small enough for **GAUSS** to bring into memory all at once. You know it has 100 observations and 3 variables, namely **state**, **expense**, and **income**. Assuming the format is as follows:

## 2. LINEAR REGRESSION

OHIO	322	7812
PA	412	7733
S_DAK	321	6841
UTAH	417	6622
WASH	415	8450
WYO	500	9096
.	.	.
.	.	.
.	.	.

Use the following commands in a **GAUSS** program file.

```
load data[100,3] = income.prn;    /* LOTUS PRN FILE */
dataname = "mydata";
/*---- NOTE: STATE IS A CHARACTER VARIABLE ----*/
varname = { "state", EXPENSE, INCOME };
/*-----*/
call saved(data,dataname,varname);
```

2. You have a large ASCII file, also generated from Lotus 1-2-3, that is too large to load into memory at one time. You can use **ATOG**. Here is an example of an **ATOG** command file:

```
input big.asc;
output mydata;
invar $ race # age pay $ sex region;
```

**race**, **sex**, and **region** are character variables, and **age** and **pay** are numeric variables. To run the above command file from **GAUSS**, type the following:

```
ATOG cmdfile;
```

where **cmdfile** is the name of the **ATOG** command file.

For more details, see the *UTILITIES* section of the **GAUSS SYSTEM AND GRAPHICS MANUAL**.

3. You already have a **GAUSS** data set and want to create a new **GAUSS** data set from the existing one. You can use **DATALOOP**.

Once you have a **GAUSS** data set, you can use the keyword **DATALIST** to view its contents. The syntax is:

```
DATALIST filename [variables];
```

For details, see **DATALIST** in the **GAUSS COMMAND REFERENCE**.

## 2.4 Compiling the Applications Procedures

By compiling your procedures and saving the compiled code to disk, you can eliminate the time required to compile the applications procedure into memory. The compiled file saved to disk will have a `.gcg` extension.

To create a file containing the compiled images of the procedures you use together often, you may, for example, type the following commands from the command line:

```
new;
library lr;
external proc lreg, l2sls;
saveall procset1;
```

The procedures listed in the **EXTERNAL** statement will be compiled and the compiled images will be saved to the file `procset1.gcg`. The file containing the compiled image should be saved on a subdirectory listed in the `SRC_PATH` of the **GAUSS** configuration file.

To use these procedures, you need to have the statement

```
use procset1;
```

at the top of your command file. The **USE** command will look along the `SRC_PATH` for the file you specify. A **LIBRARY** statement may not be necessary if you are only using procedures that are saved in the file specified in the **USE** statement.

## 2.5 Troubleshooting

Here are common error messages that you may encounter when using *LINEAR REGRESSION* procedures.

```
Undefined symbols:
LRSET      d:\app\ls\test2.e(6)
L3SLS      d:\app\ls\test2.e(22)
LRTEST     d:\app\ls\test2.e(23)
.
.
.
```

or

```

Undefined symbols:
  LRSET      d:\app1\ls\$xrun$.tmp(11)
  L3SLS      d:\app1\ls\$xrun$.tmp(37)
  LRTEST     d:\app1\ls\$xrun$.tmp(39)
  .
  .
  .

```

If this happens, the LR library may not be active. Check if the following statement is listed at the top of your command file.

```
library lr;
```

## 2.6 Error Codes

When certain errors are encountered in the specification of the model or the data being analyzed, the procedures either terminate with an error message or return an error code. This is controlled with the low order bit of the trap flag. See **TRAP** in the **GAUSS COMMAND REFERENCE**.

**TRAP 0**    terminate with error message

**TRAP 1**    return scalar error code

### 2.6.1 Testing for Error Codes

The returning error code appears as a missing value if printed, use **SCALERR** to retrieve the error number.

```

trap 1;          /* INITIALIZE THE TRAP */
Q = lreg(dataset,dv,iv,restrict);
if scalerr(Q);
    print "Error " scalerr(Q) " was encountered.";
end;
endif;
trap 0;          /* RESET THE TRAP */

```

Use **LRERROR** to display the error message associated with an error code.

```

/*****
Program file: testerr1.e
Data file:   T11_3

```



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```

+++++*/

library lr;
lrset;
dataset = "t11_3";
output file = testerr1.out reset;
trap 1;          /* INITIALIZE THE TRAP */
dv = { y };
iv = { const,p1,p3 };
restrict = "p1 + p33 = 1";      /* USER MISTYPES P3 */
eq1 = lreg(dataset,dv,iv,restrict);
if scalerr(eq1);
    lrerror("Error located in the 1st equation",eq1);
    pause(3);
endif;

dv = { y };
iv = { const,p1,p4 }; /* VARIABLE P4 IS NOT IN THE DATA SET */
eq2 = lreg(dataset,dv,iv,0);
if scalerr(eq2);
    lrerror("Error located in the 2nd equation",eq2);
    pause(3);
endif;
trap 0;          /* RESET THE TRAP */
output off;

```

NOTE: The example files are included in the `examples` directory.

### 2.6.2 List of Error Codes

Following is a list of error code definitions:

- 1** data file not found.
- 2** variables specified not found in the data set.
- 21** misspecification in the restriction string.
- 22** the restricted equations are inconsistent.
- 23** the restricted equations are linearly dependent.
- 30** system singular.
- 31** there are fewer observations than parameters to estimate.
- 36** variables specified are not consistent.
- 40** the packed output vector is empty.
- 74** the file for residual diagnostics cannot be opened.
- 75** there is not enough disk space to write the residual measures.

## 2.7 Using the On-Line Help System

If the LR library is active, all of the procedures are automatically accessible through **GAUSS**'s on-line help system.

### UNIX

Enter `help` at the command prompt.

```
(gauss) help
(help) Help on: lreg
```

### DOS

Press Alt-H, then “H” again, and enter the name of the procedure.

The help system uses the same search path that **GAUSS** uses when it is attempting to compile your command files. That is, if the help system can find the procedure you request information on, then **GAUSS** can too. This feature can be particularly useful if you are getting “Undefined symbol” errors, or if it appears that **GAUSS** is finding the wrong definition of a procedure being called.

If, when you attempt to locate the procedure through the help system, nothing appears on the screen or you are returned to your edit file or command mode, then **GAUSS** is not finding the procedure you requested. Check your `SRC_PATH`, and check to see that the LR library is active. If a file is found, the full pathname of the file is listed on the help screen.

## Chapter 3

# Topics in Linear Regression

This chapter covers a wide variety of application examples in Linear Regression, from the estimation of single equations to systems of equations. The examples cover the following topics:

1. Tests for heteroskedasticity
2. Test of structural change
3. Estimating a translog cost function using *Ordinary Least Squares*
4. Estimating a system of cost share equations using of *Seemingly Unrelated Regression*
5. Estimating Klein's Model I using *Three-Stage Least Squares*

*In order to run some of the examples below, the **DATALOOP** must be turned on with **Ctrl-T** or from the **Alt-C** configuration menu. If you have the UNIX version of **GAUSS**, use the **config** command (when running in terminal mode) or the **Config** button (when in X Windows mode).*

### 3.1 Tests for Heteroskedasticity

Heteroskedasticity exists when the errors do not have a constant variance. Its consequences leads to inefficient least squares estimators and biased estimator of the variances. Any inferences based on these estimates could be misleading. There are several tests which can detect the existence of heteroskedasticity. Two of them are discussed below.

### 3.1.1 The Breusch-Pagan Test

This is a Lagrange Multiplier test and covers a wide range of heteroskedastic situations. It assumes the model disturbances are distributed normally with variance as follows:

$$\sigma_i^2 = \sigma^2 f(\alpha^0 + Z_i' \alpha)$$

where  $f$  is any unspecified functional form.  $Z_i$  is a vector of variables which you suspect influence the heteroskedasticity, and  $\alpha$  is a vector of coefficients. If  $\alpha = 0$ , the model is said to be homoskedastic.

Procedures for this test are given as below:

1. Run the **LREG** and obtain both the residual vector ( $RES$ ) and the residual sum of squares ( $SSE$ ).
2. Calculate the  $\tilde{\sigma}^2$  as follows:

$$\tilde{\sigma}^2 = \frac{sse}{n}$$

3. Rerun the **LREG** with the form as below and obtain  $SST$  and  $SSE$ .

$$\frac{\hat{\epsilon}_t^2}{\tilde{\sigma}^2} = \alpha_0 + Z_t' \alpha + V_t$$

where  $\hat{\epsilon}_t$  are the least squares residuals from step 1 and  $\alpha_0 = 1$ .

4. Compute the test statistic which is

$$LM = (SST - SSE)/2$$

where  $SST$  and  $SSE$  are respectively the total sum of squares and residual sum of squares obtained from step 3.

Under the null hypothesis, the test statistic is asymptotically distributed as Chi-squared with degrees of freedom equal to the number of regressors ( $k$ ) in  $Z$ . Thus, at 5% level if  $LM > \chi_{0.95}^2(k)$ , you reject the hypothesis of homoskedasticity.

#### ■ Example

In the example below,  $X_2$  is thought to be the influential variable. With the use of **LREG**, you must specify a file name to hold the residual vector and its diagnostic measures. It can be done by assigning a file name to the global variable **\_lregres** (i.e., `_lregres = "temp"`). Do not confuse  $\tilde{\sigma}^2$  and  $\hat{\sigma}^2$ .  $\tilde{\sigma}^2$  is calculated in step 3 and used  $n$  as divisor.  $\hat{\sigma}^2$  is one of the return statistics, namely  $S2$ , stored in the output vector and it uses the  $(n - k)$  as divisor.

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```
/*+++++
Program file: heter1.e
Data set:      heter1
+++++*/

library lr;
lrset;
dataset = "heter1";
outset = "heter1.out";
output file = ^outset reset;
dv = { y };
iv = { const,x2,x3 };

__output = 0;
_lregres = "temp";          /* PERFORM THE 1st REGRESSION */
Q1 = lreg(dataset,dv,iv,0);
sse = vread(Q1,"sse");
n = vread(Q1,"nobs");
newS2 = sse/n;

dataloop temp newdata;      /* CALCULATE THE NEW DEPENDENT */
  extern newS2;              /* VARIABLE AS STEP 3.          */
  make newDV = (res^2)/newS2;
  keep newDV x2;
endata;

dataset = "newdata";
dv = { newDV };
iv = { const,x2 };
Q2 = lreg(dataset,dv,iv,0); /* PERFORM THE 2nd REGRESSION */
sse = vread(Q2,"sse");
sst = vread(Q2,"sst");
chisq = (sst-sse)/2;        /* COMPUTE THE TEST STATISTIC */
format /rd 12,4;
print "Total sum of squares:  " sst;
print "Residual sum of squares: " sse;
print "Chi-Squared statistic:  " chisq;

output off;

/*+++++ end of program file ++++++*/
```

Here is the output:

```
Total sum of squares:      52.8982
```

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Residual sum of squares: 43.6927  
Chi-Squared statistic: 4.6027

By comparing the  $\chi^2_{(1)}$  value at 5% significance level, which is 3.84, you may conclude that heteroskedasticity exists in the disturbance variances.

#### 3.1.2 The Goldfeld-Quandt Test

The central idea of this test is to split the observations into two groups. And under the null hypothesis of homoskedasticity, both groups should have equal variance. Whereas under the alternative, the disturbance variances would not be the same. In this test, observations are sorted according to the magnitude of the independent variable  $X_i$ , and this variable is hypothesized to be related to the variance of disturbances. Goldfeld and Quandt suggest that a certain number of the middle observations be omitted to increase the distinction between the error variances.

The test procedures are as follows:

1. Sort the observations according to the values of  $X_i$ , where  $X_i$  is thought to be the influential variable.
2. Drop some central observations, the number ( $c$ ) to be dropped is very subjective and is not obvious.
3. Run two separate regressions, on the first and last  $(n - c)/2$  observations, and find out their corresponding residual sums of squares.
4. Compute the test statistic as follows:

$$R = \frac{SSE_2}{SSE_1}$$

where  $SSE_1$  and  $SSE_2$  are respectively the residual sums of squares from the first and second regressions.

Under the null hypothesis, the test statistic  $R$  is distributed as  $F$  with  $[(n - c - 2k)/2, (n - c - 2k)/2]$  degrees of freedom. If  $F > F_{0.95}$ , the homoskedasticity is rejected at 5 percent level.

#### ■ Example

The data used in this example is per capita expenditure on public schools and per capita income by state in 1979. Data is from the United States Department of Commerce (1979, p.157). Since the Goldfeld-Quandt test requires the data to be ordered, the **SORTD** is used to sort the data set with the income variable as the sorting key. Total number of observations is 51. Each regression is run with 17 observations. By assigning a data range to the global variable **\_\_\_range**, you run the regression with the indicated range.

### 3. TOPICS IN LINEAR REGRESSION

```

/*****
Program file: heter2.e
Data set:      heter2
*****/

library lr;
lrset;
outset = "heter2.out";
output file = ^outset reset;

/* SORT THE DATA ACCORDING TO THE VALUES OF INCOME */
sortd("heter2","newdata","income",1);

__output = 0;
dv = { expense };
iv = { const,income };

__range = { 1,17 };          /* 1st REGRESSION WITH THE */
Q1 = lreg("newdata",dv,iv,0); /* FIRST 17 OBSERVATIONS. */
sse1 = vread(Q1,"sse");

__range = { 35,51 };          /* 2nd REGRESSION WITH THE */
Q2 = lreg("newdata",dv,iv,0); /* LAST 17 OBSERVATIONS. */
sse2 = vread(Q2,"sse");

format /rd 12,6;
print "SSE from the 1st regression:  " sse1;
print "SSE from the 2nd regression:  " sse2;
print "The F-statistic for this test: " sse2/sse1;

output off;

/***** end of program file *****/

```

Here is the output:

```

SSE from the 1st regression:  28809.327473
SSE from the 2nd regression:  86642.410198
The F-statistic for this test:    3.007443

```

Since at 5% level of significance  $F > F_{0.95}(15, 15)$ , where  $F_{0.95} = 2.4$ , you would reject the hypothesis of homoskedasticity.

### 3.2 Test of Structural Change

The *Chow* test is one of several ways for testing the differences in parameter estimates across data sets. Suppose you have two data sets:

$$Y_i = X_i\beta_i + \varepsilon_i \quad i = 1, 2$$

where  $Y_i$  has  $n_1$  observations,  $Y_2$  has  $n_2$  observations,  $X_1$ , and  $X_2$  have the same number of regressors  $k$ . In matrix notation, the two regressions can be expressed as follows:

$$Y = \begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix} = \begin{bmatrix} X_1 & 0 \\ 0 & X_2 \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \end{bmatrix} = X\beta + \varepsilon \quad (1)$$

Equation (1) is the unrestricted form of the model. Its residual sum of squares can be obtained from the two separate regressions (i.e.,  $e'e = e'_1e_1 + e'_2e_2$ ).

To test whether  $\beta_1 = \beta_2$ , we specify the restricted model:

$$Y = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} \beta_1 + \varepsilon = X^*\beta_1 + \varepsilon \quad (2)$$

The test statistic for the null hypothesis is an  $F$  statistic and is defined as follows:

$$F = \frac{(e'_*e_* - e'e)/k}{e'e/(n_1 + n_2 - 2k)}$$

where  $e'_*e_*$  and  $e'e$  are respectively the restricted and unrestricted residual sums of squares,  $n_1$  is the number of observations in the first sample,  $n_2$  is the number of observations in the second sample, and  $k$  is the number of regressors.

Under the null hypothesis, if  $F > F_{0.95}(k, n_1 + n_2 - 2k)$ , you would reject the hypothesis at the 5% level that the coefficient vectors are the same in two samples.

#### ■ Example

This example is from Maddala [12, page 131]. The data set, `chow.dat`, presents data on per capita food consumption, price of food and per capita income for the years: 1927-1941 and 1948-1962. We wish to test the stability of the parameters in the demand function between the two periods. The estimated function is as follows:



### 3. TOPICS IN LINEAR REGRESSION

$$\ln q = \alpha + \beta_1 \ln P + \beta_2 \ln Y$$

where  $q$  is the food consumption per capita,  $P$  is the food price, and  $Y$  is the consumer income.

Since the data needs to be in logged, **DATALOOP** is used to transform the data. Three regressions are run with the desired range of data in order to generate their corresponding residual sums of squares. Finally the test statistic is calculated. Note that the global variable **\_\_range** is used to control the data range to be passed into the regressions.

### 3. TOPICS IN LINEAR REGRESSION

```
/*+++++
Program file: chow.e
Data set:      chow
+++++*/

library lr;
lrset;

dataloop chow newdata;
  consume = ln(consume);  /* TAKE NATURAL LOG FOR VARIABLES */
  price = ln(price);
  income = ln(income);
endata;

output file = chow.out reset;

dv = { consume };
iv = { const,price,income };
__output = 0;

Qt = lreg("newdata",dv,iv,0);  /* FULL SAMPLE RUN */
sseR = vread(Qt,"sse");

__range = { 1,15 };  /* RUN WITH THE FIRST 15 OBSERVATIONS */
Q1 = lreg("newdata",dv,iv,0);
sse1 = vread(Q1,"sse");
n1 = vread(Q1,"nobs");

__range = { 16,30 };  /* RUN WITH THE LAST 15 OBSERVATIONS */
Q2 = lreg("newdata",dv,iv,0);
sse2 = vread(Q2,"sse");
n2 = vread(Q2,"nobs");

sseU = sse1 + sse2;  /* CALCULATE THE UNRESTRICTED SSE */
F = ((sseR - sseU)/3)/(sseU/(n1+n2-2*3));
prob = cdfc(f,3,(n1+n2-2*3));

format /rd 12,8;
print "unrestricted residual sum of squares: " sseU;
print "  restricted residual sum of squares: " sseR;
print "                                F statistic: " F;
print "                                significance level: " prob;

output off;
```

### 3. TOPICS IN LINEAR REGRESSION

```
/*+++++ end of program file ++++++*/
```

Here is the output:

```
unrestricted residual sum of squares: 0.00169541
restricted residual sum of squares: 0.00286947
F statistic: 5.53995446
significance level: 0.00491253
```

The restricted and unrestricted residual sums of squares are different from those calculated in Maddala [12, page 131]. This is due to differing presentation of the results. On page 113, Maddala uses  $10^2 \times \text{SSE}$  to present both residual sums of squares. From the  $F$ -tables,  $F_{0.95}(3, 24) = 3.01$  and  $F_{0.99}(3, 24) = 4.72$ . Thus, even at the 1% level of significance, the hypothesis of stability is rejected.

### 3.3 Estimating a Translog Cost Function Using Ordinary Least Squares

The duality of cost and production functions is an important subject in the neoclassical economics. According to the duality theory, under appropriate regularity conditions, all of the information about the solution to the production function can be obtained via the corresponding cost function. In fact, Silberberg [13] has suggested that the duality theory assures us that if a cost function satisfies some elementary properties, i.e., linear homogeneity and concavity in the factor prices, then there is also a unique production function. Homogeneity in input prices implies that when all input prices are doubled, the cost of production also doubles (i.e., mathematically,  $C(tP, Y) = t \cdot C(P, Y)$  where  $t > 0$ ,  $C$  is the cost and is function of input prices ( $P$ ) and output ( $Y$ )).

Although the topic of estimation of the cost function is very broad, some of the interesting points are presented below. This section demonstrates the practical aspects of estimating a translog cost function with symmetry and homogeneity in input prices imposed. The usage of the translog functional form is due to its popularity and flexibility.

The translog cost function is specified as below:

$$\ln C = \alpha_0 + \alpha_y \ln Y + \sum_i \alpha_i \ln P_i + \frac{1}{2} \beta_{yy} (\ln Y)^2 + \frac{1}{2} \sum_i \sum_j \beta_{ij} \cdot \ln P_i \cdot \ln P_j + \sum_i \gamma_{yi} \cdot \ln Y \cdot \ln P_i$$

### 3. TOPICS IN LINEAR REGRESSION

where  $C$  is the total cost,  $Y$  is the level of output, and  $P_i$  is the  $i^{th}$  input price. If symmetry is assumed (i.e.,  $\alpha_{ij} = \alpha_{ji} \quad \forall \quad i \neq j$ ), fewer parameters are estimated.

Several hypotheses can be tested within the function. They are constant returns to size (or linear homogeneity in output, i.e., the same idea as linear homogeneity in input prices) and functional form of the cost function (i.e., the Cobb Douglas technology). The conditions for constant returns to size are tested by restricting:  $\alpha_y = 1$ ,  $\alpha_{yy} = 0$ , and  $\alpha_{yi} = 0 \quad \forall \quad i$ . And the hypothesis regarding the Cobb Douglas technology is tested by restricting all quadratic terms and cross product terms to be zero. Both hypotheses require an  $F$ -test and the test statistic is defined in the **LRTEST** procedure.

Finally, in order to guarantee that the cost function is homogenous of degree one in input prices, some restrictions must be imposed into the function. For the translog case, it is:  $\sum_i \alpha_i = 1$ ,  $\sum_i \gamma_{yi} = 0$ , and  $\sum_j \beta_{ij} = 0 \quad \forall \quad i$ . However, if the Cobb Douglas technology can not be rejected, the following restrictions are required:  $\sum_i \alpha_i = 1$ , all quadratic terms and cross product terms are restricted to zero.

#### ■ Example

The application of **LREG** to the above problem is displayed below. Data used in this example consists of 68 observations with 5 input prices. These data have already been normalized around their geometric means. *Note that when the Cobb Douglas technology can not be rejected, the restricted equations (with Cobb Douglas specification and homogeneity in input prices imposed) are constructed to estimate the cost function again.*

```

/*****
Program file: translog.e
Data set:      translog
*****/

library lr;
lrset;
output file = translog.out reset;

dataloop translog newdata;      /* PERFORM DATA TRANSFORMATION */
  cost = ln(cost);
  y = ln(y);
  p1 = ln(p1);
  p2 = ln(p2);
  p3 = ln(p3);
  p4 = ln(p4);
  p5 = ln(p5);
  make yy = (y*y)/2;
  make p11 = (p1*p1)/2;
  make p12 = p1*p2;

```

## 3. TOPICS IN LINEAR REGRESSION

```

make p13 = p1*p3;
make p14 = p1*p4;
make p15 = p1*p5;
make p22 = (p2*p2)/2;
make p23 = p2*p3;
make p24 = p2*p4;
make p25 = p2*p5;
make p33 = (p3*p3)/2;
make p34 = p3*p4;
make p35 = p3*p5;
make p44 = (p4*p4)/2;
make p45 = p4*p5;
make p55 = (p5*p5)/2;
make yp1 = y*p1;
make yp2 = y*p2;
make yp3 = y*p3;
make yp4 = y*p4;
make yp5 = y*p5;
enddata;

dataset = "newdata";
dv = { cost };
iv = { const,y,p1,p2,p3,p4,p5,
      yy,
      p11,p12,p13,p14,p15,
      p22,p23,p24,p25,
      p33,p34,p35,
      p44,p45,
      p55,
      yp1,yp2,yp3,yp4,yp5 };
Q = lreg(dataset,dv,iv,0);

/* TEST OF CONSTANT RETURN TO SIZE */
test1 = "y=1, yy=0, yp1=0, yp2=0, yp3=0, yp4=0, yp5=0";
call lrtest(Q,test1);

/* TEST OF COBB DOUGLAS TECHNOLOGY */
test2 = "yy=0,
p11=0, p12=0, p13=0, p14=0, p15=0,
p22=0, p23=0, p24=0, p25=0,
p33=0, p34=0, p35=0,
p44=0, p45=0,
p55=0,
yp1=0, yp2=0, yp3=0, yp4=0, yp5=0";
call lrtest(Q,test2);

```

### 3. TOPICS IN LINEAR REGRESSION

```

__title = "COBB DOUGLAS TECHNOLOGY AND HOMOGENEITY IMPOSED";
restrict = "p1+p2+p3+p4+p5=1" $+ ", " $+ test2; /* note here */
call lreg(dataset,dv,iv,restrict);

output off;

/***** end of program file *****/

```

Output for this example:

```

=====
LINEAR REGRESSION:  Version 1.00 (R0)                                5/05/92   2:08 pm
=====
ANALYZING FILE: newdata

```

```

-----
Dependent variable:      COST
-----

```

Total cases:	68	Valid cases:	68
Total SS:	34.870	Degrees of freedom:	40
R-squared:	0.790	Rbar-squared:	0.648
Residual SS:	7.336	Std error of est:	0.428
F(27,40):	5.560	Probability of F:	0.000
Durbin-Watson:	1.920		

Variable	Estimate	Standard Error	t-value	Prob > t	Standardized Estimate	Cor with Dep Var
CONST	-0.743055	0.637914	-1.164819	0.251	0.000000	0.000000
Y	0.503951	0.078073	6.454869	0.000	0.652219	0.792476
P1	0.133066	0.083615	1.591409	0.119	0.587181	0.331334
P2	0.105448	0.160177	0.658322	0.514	0.083346	-0.064546
P3	0.346294	0.232256	1.491002	0.144	0.145411	0.195297
P4	-0.422912	0.817184	-0.517523	0.608	-0.195221	-0.002283
P5	-0.227474	0.205070	-1.109250	0.274	-0.140038	0.129591
YY	0.270977	0.130397	2.078093	0.044	0.218877	0.385657
P11	0.132195	0.120351	1.098415	0.279	0.397203	-0.182481
P12	-0.081801	0.060569	-1.350541	0.184	-0.181723	-0.066657
P13	-0.097157	0.082348	-1.179842	0.245	-0.134457	0.011821
P14	-0.107957	0.086415	-1.249290	0.219	-0.170307	-0.164789
P15	0.063802	0.052807	1.208222	0.234	0.119138	0.127592
P22	0.041148	0.321014	0.128183	0.899	0.027709	0.027746
P23	0.134335	0.726283	0.184962	0.854	0.020963	-0.045316
P24	-0.204401	0.495043	-0.412896	0.682	-0.061939	0.027906

### 3. TOPICS IN LINEAR REGRESSION

P25	0.194994	0.412987	0.472155	0.639	0.062974	-0.057050
P33	0.240103	1.075696	0.223207	0.825	0.024031	-0.009060
P34	-0.013950	0.997745	-0.013981	0.989	-0.001986	-0.018197
P35	0.360854	0.759751	0.474963	0.637	0.068868	-0.049615
P44	-1.563439	2.446582	-0.639030	0.526	-0.246312	-0.015852
P45	1.401099	0.950206	1.474521	0.148	0.272823	-0.169663
P55	0.029768	0.444437	0.066979	0.947	0.009755	-0.019073
YP1	0.005353	0.027006	0.198204	0.844	0.020575	0.216620
YP2	0.090026	0.299039	0.301052	0.765	0.056609	-0.062936
YP3	0.338722	0.282181	1.200371	0.237	0.127290	0.242308
YP4	-0.364306	0.277432	-1.313137	0.197	-0.152585	-0.123340
YP5	0.091478	0.293100	0.312106	0.757	0.036010	0.229466

----- LREG: Results for Linear Hypothesis Testing -----

F(7,40) statistic = 7.596 Prob. = 0.000

----- LREG: Results for Linear Hypothesis Testing -----

F(21,40) statistic = 0.940 Prob. = 0.548

===== COBB DOUGLAS TECHNOLOGY AND HOMOGENEITY IMPOSED =====

===== LINEAR REGRESSION: Version 1.00 (R0) 5/05/92 2:08 pm =====

===== ANALYZING FILE: newdata =====

RESTRICTIONS IN EFFECT

-----  
Dependent variable: COST  
-----

Total cases:	68	Valid cases:	68
Total SS:	34.870	Degrees of freedom:	62
R-squared:	0.654	Rbar-squared:	0.626
Residual SS:	12.067	Std error of est:	0.441
F(5,62):	23.433	Probability of F:	0.000
Durbin-Watson:	2.128		

Variable	Estimate	Standard Error	t-value	Prob > t	Standardized Estimate	Cor with Dep Var
-----						

### 3. TOPICS IN LINEAR REGRESSION

CONST	0.000000	0.053499	0.000000	1.000	0.000000	0.000000
Y	0.588345	0.061114	9.627047	0.000	0.761442	0.792476
P1	0.033788	0.018047	1.872239	0.066	0.149095	0.331334
P2	0.176374	0.087734	2.010317	0.049	0.139406	-0.064546
P3	0.640062	0.162847	3.930453	0.000	0.268765	0.195297
P4	0.064513	0.137881	0.467890	0.642	0.029780	-0.002283
P5	0.085264	0.122994	0.693239	0.491	0.052491	0.129591
YY	0.000000	0.000000	0.000000	1.000	0.000000	0.385657
P11	0.000000	0.000000	0.000000	1.000	0.000000	-0.182481
P12	0.000000	0.000000	0.000000	1.000	0.000000	-0.066657
P13	0.000000	0.000000	0.000000	1.000	0.000000	0.011821
P14	-0.000000	0.000000	-0.000000	1.000	-0.000000	-0.164789
P15	-0.000000	0.000000	-0.000000	1.000	-0.000000	0.127592
P22	0.000000	0.000000	0.000000	1.000	0.000000	0.027746
P23	0.000000	0.000000	0.000000	1.000	0.000000	-0.045316
P24	0.000000	0.000000	0.000000	1.000	0.000000	0.027906
P25	0.000000	0.000000	0.000000	1.000	0.000000	-0.057050
P33	0.000000	0.000000	0.000000	1.000	0.000000	-0.009060
P34	-0.000000	0.000000	-0.000000	1.000	-0.000000	-0.018197
P35	0.000000	0.000000	0.000000	1.000	0.000000	-0.049615
P44	0.000000	0.000000	0.000000	1.000	0.000000	-0.015852
P45	0.000000	0.000000	0.000000	1.000	0.000000	-0.169663
P55	-0.000000	0.000000	-0.000000	1.000	-0.000000	-0.019073
YP1	-0.000000	0.000000	-0.000000	1.000	-0.000000	0.216620
YP2	-0.000000	0.000000	-0.000000	1.000	-0.000000	-0.062936
YP3	-0.000000	0.000000	-0.000000	1.000	-0.000000	0.242308
YP4	-0.000000	0.000000	-0.000000	1.000	-0.000000	-0.123340
YP5	-0.000000	0.000000	-0.000000	1.000	-0.000000	0.229466

By looking at the results, the test of constant returns to size is rejected. However, the Cobb Douglas technology can not be rejected at even 1% level of significance. Therefore, the cost function is estimated again with the Cobb Douglas technology and homogeneity in input prices imposed. Alternatively, you can estimate the Cobb Douglas functional form as below.

$$\ln C = \alpha_0 + \alpha_y \ln Y + \sum_i \alpha_i \ln P_i$$

With homogeneity imposed ( $\sum_i \alpha_i = 1$ ), both estimations should give identical results. You can confirm this by trying the following lines in the command file.

```
restrict = "p1+p2+p3+p4+p5=1";
dv = { cost };
iv = { const,y,p1,p2,p3,p4,p5 };
call lreg(dataset,dv,iv,restrict);
```



### 3.4 Estimating a System of Cost Share Equations Using Seemingly Unrelated Regression

This section demonstrates the use of **LSUR** to estimate the system of cost shares with seemingly unrelated regression technique. Linear hypothesis testing and restrictions imposed on the parameters are demonstrated as well.

The system of cost shares are defined as follows:

$$S_{it} = \alpha_i + \sum_j \alpha_{ij} \ln P_{jt} + \gamma_i \ln Y_t + \beta_i trend + \varepsilon_{it} \quad i = 1, 2, 3, 4$$

where  $S_i$  are the cost shares and derived from the translog cost function,  $trend$  is a time trend (that is,  $t = 1$  for the first observation,  $t = 2$  for the second observation, and so on),  $P_j$  is the  $j^{th}$  input price, and  $Y$  is the output.

There are several hypotheses of interest:

1. Symmetry  $\alpha_{ij} = \alpha_{ji} \quad \forall \quad i \neq j$
2. Homogeneity  $\sum_j \alpha_{ij} = 0 \quad \forall \quad i$  and  $\sum_i \alpha_i = 1$
3. Constant returns to scale  $\gamma_i \quad \forall \quad i$
4. No technical change  $\beta_i \quad \forall \quad i$

Besides the above hypotheses, you may want to estimate the systems with (1) and (2) above imposed. Since the shares must add to unity, one equation must be dropped to prevent a singular variance-covariance matrix. Kmenta and Gilbert [11] have shown that the *Iterative Seemingly-Unrelated Regression* can produce asymptotically maximum likelihood estimates. The parameter estimates are the same whichever equation is deleted.

#### ■ Example

The program file for this problem is **shares.e**. This system model has four input prices, thus it has four equations. However, because of the problem of the singular variance-covariance matrix, the 4<sup>th</sup> equation is dropped from the model. To illustrate that it is irrelevant which equation is dropped, the final model reestimates with the 4<sup>th</sup> equation included and the 1<sup>st</sup> equation excluded. Data for this example are put into two files, **share.dat** and **price.dat**. Although the merging of two data files is not presently available in **DATALOOP**, you can use the **GAUSS** language to implement this. If you have difficulty seeing how the restrictions are constructed, try to write out the share equations. More details of the **LSUR** procedure can be found in the command reference of the next chapter.

### 3. TOPICS IN LINEAR REGRESSION

```

/*****
Program file: shares.e
Data set:      share
*****/

/* THIS PART IS TO COMBINE TWO DATA SETS */
vnames = getname("share")|getname("price");
open f1 = share;
open f2 = price;
create fout = newdata with ^vnames,0,8;

do until eof(f1);
  data = readr(f1,100)~readr(f2,100);
  data = data[.,1:4]~ln(data[.,5:10])~data[.,11];
  if writer(fout,data) /= rows(data);
    print "disk full"; end;
  endif;
endo;
closeall;

library lr;
lrset;
output file = shares.out reset;

y = { s1,s2,s3 };
x = { const,p1,p2,p3,p4,y,trend,      /* 1st EQN. */
      const,p1,p2,p3,p4,y,trend,      /* 2nd EQN. */
      const,p1,p2,p3,p4,y,trend };    /* 3rd EQN. */
novars = { 7,7,7 };                  /* NO. OF RHS VARIABLES IN EACH EQN. */

Q = lsur("newdata",y,x,novars,0);

/* TEST OF SYMMETRY */
print "TEST OF SYMMETRY ";
test1 = "p2:1-p1:2=0, p3:1-p1:3=0, p3:2-p2:3=0";
call lrtest(Q,test1);

/* TEST OF HOMOGENEITY */
print "TEST OF HOMOGENEITY ";
test2 = "p1:1 + p2:1 + p3:1 + p4:1 = 0,
         p1:2 + p2:2 + p3:2 + p4:2 = 0,
         p1:3 + p2:3 + p3:3 + p4:3 = 0";
call lrtest(Q,test2);

/* TEST OF CONSTANT RETURNS TO SCALE */
print "TEST OF CONSTANT RETURNS TO SCALE ";
```

### 3. TOPICS IN LINEAR REGRESSION

```

test3 = "y:1=0, y:2=0, y:3=0";
call lrtest(Q,test3);

/* TEST OF NO TECHNICAL CHANGE */
print "TEST OF NO TECHNICAL CHANGE ";
test4 = "trend:1=0, trend:2=0, trend:3=0";
call lrtest(Q,test4);

/* SYMMETRY AND HOMOGENEITY IMPOSED */
_lrtol = 0.00000001;
_lriter = 100;
__title = "SYMMETRY AND HOMOGENEITY IMPOSED USING S1,S2,S3";
restrict = "p2:1-p1:2=0,
           p3:1-p1:3=0,
           p3:2-p2:3=0,
           p1:1 + p2:1 + p3:1 + p4:1 = 0,
           p1:2 + p2:2 + p3:2 + p4:2 = 0,
           p1:3 + p2:3 + p3:3 + p4:3 = 0";
call lsur("newdata",y,x,novars,restrict);

/* USING S4 AND REMOVING S1 */
y = { s2,s3,s4 };
x = { const,p1,p2,p3,p4,y,trend,
      const,p1,p2,p3,p4,y,trend,
      const,p1,p2,p3,p4,y,trend };
novars = { 7,7,7 };
_lrtol = 0.00000001;
_lriter = 100;
__title = "SYMMETRY AND HOMOGENEITY IMPOSED USING S2,S3,S4";
restrict = "p3:1-p2:2=0,
           p4:1-p2:3=0,
           p4:2-p3:3=0,
           p1:1 + p2:1 + p3:1 + p4:1 = 0,
           p1:2 + p2:2 + p3:2 + p4:2 = 0,
           p1:3 + p2:3 + p3:3 + p4:3 = 0";
call lsur("newdata",y,x,novars,restrict);

output off;

/***** end of program file *****/

```

Output for the example:

From the output below, there are two interesting results. First, all of the hypotheses are rejected at any level of significance. It seems to be somewhat disappointing owing

### 3. TOPICS IN LINEAR REGRESSION

to the violation of the economic theory (i.e., the conditions of symmetry and homogeneity). However, these conditions are seldom tested. In fact, according to Young et al. [17] in most previous studies that have used the flexible functional forms, the properties of the cost function such as the curvature condition is either not tested or rejected. This applies as well to the homogeneity condition. In standard practice, the symmetry and homogeneity are imposed in an ad hoc manner. Second, you can confirm that the *Iterative Seemingly Unrelated Regression* can produce asymptotically maximum likelihood estimates (i.e., obtained parameter estimates are invariant which respect to which equation is deleted) by excluding a different equation.

```
=====
LINEAR SEEMINGLY UNRELATED REGRESSION:  Version 1.00   4/04/92  12:06 pm
=====
ANALYZING FILE: newdata
```

DIVISOR USING N IN EFFECT

```
ITER. # =    0    LOG OF DETERMINANT OF SIGMA =   -28.63610569
ITER. # =    1    LOG OF DETERMINANT OF SIGMA =   -28.63610569
```

```
-----
Equation:    1
Dependent variable:      S1
-----
```

Total cases:	51	Valid cases:	51
Total SS:	0.143	Degrees of freedom:	----
R-squared:	0.973	Rbar-squared:	0.970
Residual SS:	0.004	Std error of est:	0.009
Durbin-Watson:	0.866		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	0.42061914	0.03214251	13.086	0.0000
P1	0.40079591	0.01905988	21.028	0.0000
P2	-0.06503234	0.03126903	-2.080	0.0434
P3	-0.00663223	0.02213495	-0.300	0.7659
P4	-0.01302998	0.01050634	-1.240	0.2215
Y	-0.35219294	0.04038780	-8.720	0.0000
TREND	0.00064332	0.00086750	0.742	0.4623

```
-----
Equation:    2
Dependent variable:      S2
-----
```

### 3. TOPICS IN LINEAR REGRESSION

Total cases:	51	Valid cases:	51
Total SS:	0.110	Degrees of freedom:	----
R-squared:	0.875	Rbar-squared:	0.858
Residual SS:	0.014	Std error of est:	0.016
Durbin-Watson:	0.496		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	0.25782323	0.06079927	4.241	0.0001
P1	-0.42352146	0.03605278	-11.747	0.0000
P2	-0.00105493	0.05914705	-0.018	0.9859
P3	-0.05348148	0.04186944	-1.277	0.2082
P4	-0.04980891	0.01987330	-2.506	0.0160
Y	0.50219016	0.07639569	6.574	0.0000
TREND	0.00112845	0.00164093	0.688	0.4953

-----  
Equation: 3  
Dependent variable: S3  
-----

Total cases:	51	Valid cases:	51
Total SS:	0.044	Degrees of freedom:	----
R-squared:	0.939	Rbar-squared:	0.931
Residual SS:	0.003	Std error of est:	0.007
Durbin-Watson:	0.724		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	-0.03571263	0.02678922	-1.333	0.1894
P1	-0.05133372	0.01588548	-3.231	0.0023
P2	-0.09499125	0.02606122	-3.645	0.0007
P3	0.01786662	0.01844840	0.968	0.3381
P4	-0.02318483	0.00875652	-2.648	0.0112
Y	0.10671202	0.03366127	3.170	0.0028
TREND	0.00331548	0.00072302	4.586	0.0000

#### TEST OF SYMMETRY

----- LSUR: Results for Linear Hypothesis Testing -----

Wald Chi-SQ(3) statistic = 76.032 Prob. = 0.000

#### TEST OF HOMOGENEITY

### 3. TOPICS IN LINEAR REGRESSION

----- LSUR: Results for Linear Hypothesis Testing -----

Wald Chi-SQ(3) statistic = 108.365      Prob. = 0.000

TEST OF CONSTANT RETURNS TO SCALE

----- LSUR: Results for Linear Hypothesis Testing -----

Wald Chi-SQ(3) statistic = 158.533      Prob. = 0.000

TEST OF NO TECHNICAL CHANGE

----- LSUR: Results for Linear Hypothesis Testing -----

Wald Chi-SQ(3) statistic = 56.880      Prob. = 0.000

=====

SYMMETRY AND HOMOGENEITY IMPOSED USING S1,S2,S3

=====

LINEAR SEEMINGLY UNRELATED REGRESSION: Version 1.00    4/04/92    12:06 pm

=====

ANALYZING FILE: newdata

DIVISOR USING N IN EFFECT  
RESTRICTIONS IN EFFECT

ITER. # =	0	LOG OF DETERMINANT OF SIGMA =	-27.33021909
ITER. # =	1	LOG OF DETERMINANT OF SIGMA =	-27.39912399
ITER. # =	2	LOG OF DETERMINANT OF SIGMA =	-27.39948493
ITER. # =	3	LOG OF DETERMINANT OF SIGMA =	-27.39948665
ITER. # =	4	LOG OF DETERMINANT OF SIGMA =	-27.39948666
ITER. # =	5	LOG OF DETERMINANT OF SIGMA =	-27.39948666

-----

Equation:    1

Dependent variable:      S1

-----

Total cases:	51	Valid cases:	51
Total SS:	0.143	Degrees of freedom:	----
R-squared:	0.954	Rbar-squared:	0.954
Residual SS:	0.007	Std error of est:	0.011

### 3. TOPICS IN LINEAR REGRESSION

Durbin-Watson: 0.729

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	0.32351807	0.02125978	15.217	0.0000
P1	0.29551004	0.01140614	25.908	0.0000
P2	-0.23185846	0.01478196	-15.685	0.0000
P3	-0.00831974	0.00834634	-0.997	0.3237
P4	-0.05533185	0.00707085	-7.825	0.0000
Y	-0.12711952	0.01089636	-11.666	0.0000
TREND	0.00299290	0.00064649	4.629	0.0000

Equation: 2  
Dependent variable: S2

Total cases:	51	Valid cases:	51
Total SS:	0.110	Degrees of freedom:	----
R-squared:	0.802	Rbar-squared:	0.802
Residual SS:	0.022	Std error of est:	0.021
Durbin-Watson:	0.259		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	0.37307088	0.03770198	9.895	0.0000
P1	-0.23185846	0.01478196	-15.685	0.0000
P2	0.23773082	0.02815147	8.445	0.0000
P3	-0.02367121	0.01692764	-1.398	0.1682
P4	0.01779884	0.01343222	1.325	0.1912
Y	0.10516417	0.01698785	6.191	0.0000
TREND	-0.00149076	0.00113327	-1.315	0.1944

Equation: 3  
Dependent variable: S3

Total cases:	51	Valid cases:	51
Total SS:	0.044	Degrees of freedom:	----
R-squared:	0.926	Rbar-squared:	0.926
Residual SS:	0.003	Std error of est:	0.008
Durbin-Watson:	0.648		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
----------	-----------------------	----------------	---------	----------

### 3. TOPICS IN LINEAR REGRESSION

CONST	0.00535612	0.02658260	0.201	0.8411
P1	-0.00831974	0.00834634	-0.997	0.3237
P2	-0.02367121	0.01692764	-1.398	0.1682
P3	0.03282478	0.01975992	1.661	0.1029
P4	-0.00083384	0.00634676	-0.131	0.8960
Y	0.00065254	0.00891954	0.073	0.9420
TREND	0.00229339	0.00073096	3.138	0.0028

=====

SYMMETRY AND HOMOGENEITY IMPOSED USING S2,S3,S4

=====

=====

LINEAR SEEMINGLY UNRELATED REGRESSION: Version 1.00 4/04/92 12:06 pm

=====

ANALYZING FILE: newdata

DIVISOR USING N IN EFFECT  
RESTRICTIONS IN EFFECT

ITER. # =	0	LOG OF DETERMINANT OF SIGMA =	-27.26517712
ITER. # =	1	LOG OF DETERMINANT OF SIGMA =	-27.39866015
ITER. # =	2	LOG OF DETERMINANT OF SIGMA =	-27.39948790
ITER. # =	3	LOG OF DETERMINANT OF SIGMA =	-27.39949111
ITER. # =	4	LOG OF DETERMINANT OF SIGMA =	-27.39949112
ITER. # =	5	LOG OF DETERMINANT OF SIGMA =	-27.39949112

-----

Equation: 1

Dependent variable: S2

-----

Total cases:	51	Valid cases:	51
Total SS:	0.110	Degrees of freedom:	----
R-squared:	0.802	Rbar-squared:	0.802
Residual SS:	0.022	Std error of est:	0.021
Durbin-Watson:	0.259		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	0.37306890	0.03770206	9.895	0.0000
P1	-0.23185685	0.01478201	-15.685	0.0000
P2	0.23773025	0.02815156	8.445	0.0000
P3	-0.02367155	0.01692765	-1.398	0.1682
P4	0.01779815	0.01343223	1.325	0.1912
Y	0.10516289	0.01698791	6.190	0.0000
TREND	-0.00149070	0.00113328	-1.315	0.1944



### 3. TOPICS IN LINEAR REGRESSION

```

-----
Equation: 2
Dependent variable: S3
-----

Total cases: 51 Valid cases: 51
Total SS: 0.044 Degrees of freedom: ----
R-squared: 0.926 Rbar-squared: 0.926
Residual SS: 0.003 Std error of est: 0.008
Durbin-Watson: 0.648

```

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	0.00535567	0.02658261	0.201	0.8411
P1	-0.00831953	0.00834633	-0.997	0.3237
P2	-0.02367155	0.01692765	-1.398	0.1682
P3	0.03282497	0.01975992	1.661	0.1029
P4	-0.00083389	0.00634676	-0.131	0.8960
Y	0.00065231	0.00891954	0.073	0.9420
TREND	0.00229341	0.00073096	3.138	0.0028

```

-----
Equation: 3
Dependent variable: S4
-----

Total cases: 51 Valid cases: 51
Total SS: 0.110 Degrees of freedom: ----
R-squared: 0.918 Rbar-squared: 0.918
Residual SS: 0.009 Std error of est: 0.013
Durbin-Watson: 0.328

```

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	0.29805475	0.02261700	13.178	0.0000
P1	-0.05533192	0.00707086	-7.825	0.0000
P2	0.01779815	0.01343223	1.325	0.1912
P3	-0.00083389	0.00634676	-0.131	0.8960
P4	0.03836766	0.00942412	4.071	0.0002
Y	0.02130335	0.00941229	2.263	0.0280
TREND	-0.00379559	0.00068982	-5.502	0.0000

### 3.5 Estimating Klein's Model I Using Three-Stage Least Squares

This example uses the Klein's Model I [10] for illustration of two- and three-stage least squares. The three behavioral equations are:

$$C = \alpha_0 + \alpha_1 P + \alpha_2 P_{-1} + \alpha_3 (W_p + W_g) + \varepsilon_1 \quad (1)$$

$$I = \beta_0 + \beta_1 P + \beta_2 P_{-1} + \beta_3 K_{-1} + \varepsilon_2 \quad (2)$$

$$W_p = \gamma_0 + \gamma_1 X + \gamma_2 X_{-1} + \gamma_3 A + \varepsilon_3 \quad (3)$$

Equations 1 to 3 are respectively the consumption equation, investment equation, and demand-for-labour equation; where

$C$	=	Consumption
$P$	=	Profits
$P_{-1}$	=	Profits lagged one year
$W_p$	=	Private wage bill
$W_g$	=	Government wage bill
$K_{-1}$	=	Capital stock at the beginning of the year
$Y$	=	National income
$T$	=	Indirect taxes
$X$	=	$Y + T - W_g$
$A$	=	time trend measured as years from 1931

The model is completed by the following three identities:

$$\begin{aligned} Y + T &= C + I + G \\ Y &= W_p + W_g + P \\ K &= K_{-1} + I \end{aligned}$$

where  $G$  is government spending on goods and services.

This above system includes six endogenous variables ( $C, P, W_p, I, Y, K$ ) and seven predetermined variables ( $W_g, T, G, A, P_{-1}, K_{-1}, (Y + T - W_g)_{-1}$ ). All three behavioral equations are overidentified. According to Zellner and Theil [18], the three identities should be removed from the estimation.

### 3. TOPICS IN LINEAR REGRESSION

#### ■ Example

From the data set, some variables such as the lagged variables and the time trend are not available. Hence, we demonstrate the use of the **DATALOOP** to create a new data set. Inside the **DATALOOP** the **LAGs** are used to create the lagged variables. Iteration of the estimation process and parameters restriction across equations are available inside the **L3SLS** procedure. Details of these can be found in the command reference of the next chapter.

```

/*****
Program file: klein.e
Data set:      klein
*****/

library lr;
lrset;
dataloop klein newdata;  /* GENERATE NEW DATA SET */
    make wsum = wp + wg;
    make trend = year - 1931;
    lag klag = k:1;
    lag plag = p:1;
    lag xlag = x:1;
    keep year c p wp i x wg g t k wsum trend klag plag xlag;
endata;

output file = Klein.out reset;
lhs = { c,i,wp };          /* L.H.S. VARIABLES FOR THE MODEL */
rhs = { const,p,plag,wsum, /* R.H.S. VARIABLES FOR 1ST EQN. */
        const,p,plag,klag, /* 2ND EQUATION */
        const,x,xlag,trend }; /* 3RD EQUATION */
exo = { const,wg,t,g,trend,plag,klag,xlag }; /* EXOGENOUS VAR. */
novars = { 4,4,4 }; /* NO. OF R.H.S. VARIABLE IN EACH EQN. */

_lrdv = 0; /* USE THE NORMAL DIVISOR */
Q = l3sls("newdata",lhs,rhs,exo,novars,0);

output off;

/***** end of program file *****/

```

Here is the output:

```

=====
LINEAR THREE-STAGE LEAST SQUARES: Version 1.00 (R0) 4/02/92 11:12 am

```

### 3. TOPICS IN LINEAR REGRESSION

=====

ANALYZING FILE: newdata

\*\*\*\*\* TWO-STAGE RESULTS \*\*\*\*\*

-----

Equation: 1

Dependent variable: C

-----

Total cases:	22	Valid cases:	21
Total SS:	941.430	Degrees of freedom:	17
R-squared:	0.977	Rbar-squared:	0.973
Residual SS:	21.925	Std error of est:	1.136
Durbin-Watson:	1.485		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	16.55475577	1.46797870	11.277	0.0000
P	0.01730221	0.13120458	0.132	0.8966
PLAG	0.21623404	0.11922168	1.814	0.0874
WSUM	0.81018270	0.04473506	18.111	0.0000

-----

Equation: 2

Dependent variable: I

-----

Total cases:	22	Valid cases:	21
Total SS:	252.327	Degrees of freedom:	17
R-squared:	0.885	Rbar-squared:	0.865
Residual SS:	29.047	Std error of est:	1.307
Durbin-Watson:	2.085		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	20.27820894	8.38324890	2.419	0.0271
P	0.15022182	0.19253359	0.780	0.4460
PLAG	0.61594358	0.18092585	3.404	0.0034
KLAG	-0.15778764	0.04015207	-3.930	0.0011

-----

Equation: 3

Dependent variable: WP

### 3. TOPICS IN LINEAR REGRESSION

```

-----
Total cases:           22    Valid cases:           21
Total SS:              794.910  Degrees of freedom:      17
R-squared:             0.987    Rbar-squared:           0.985
Residual SS:          10.005    Std error of est:       0.767
Durbin-Watson:         1.963

```

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	1.50029689	1.27568637	1.176	0.2558
X	0.43885907	0.03960266	11.082	0.0000
XLAG	0.14667382	0.04316395	3.398	0.0034
TREND	0.13039569	0.03238839	4.026	0.0009

\*\*\*\*\* THREE-STAGE RESULTS \*\*\*\*\*

```

ITER. # = 0    LOG OF DETERMINANT OF SIGMA = -0.61186241
ITER. # = 1    LOG OF DETERMINANT OF SIGMA = -0.62839294

```

```

-----
Equation: 1
Dependent variable: C
-----

```

```

Total cases:           22    Valid cases:           21
Total SS:              941.430  Degrees of freedom:      17
R-squared:             0.980    Rbar-squared:           0.977
Residual SS:          18.727    Std error of est:       1.050
Durbin-Watson:         1.425

```

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	16.44079006	1.44992488	11.339	0.0000
P	0.12489047	0.12017872	1.039	0.3133
PLAG	0.16314409	0.11163081	1.461	0.1621
WSUM	0.79008094	0.04216562	18.738	0.0000

```

-----
Equation: 2
Dependent variable: I
-----

```

```

Total cases:           22    Valid cases:           21
Total SS:              252.327  Degrees of freedom:      17

```

### 3. TOPICS IN LINEAR REGRESSION

R-squared:	0.826	Rbar-squared:	0.795
Residual SS:	43.954	Std error of est:	1.608
Durbin-Watson:	1.996		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	28.17784687	7.55085338	3.732	0.0016
P	-0.01307918	0.17993761	-0.073	0.9429
PLAG	0.75572396	0.16997567	4.446	0.0004
KLAG	-0.19484825	0.03615585	-5.389	0.0000

-----  
Equation: 3  
Dependent variable: WP  
-----

Total cases:	22	Valid cases:	21
Total SS:	794.910	Degrees of freedom:	17
R-squared:	0.986	Rbar-squared:	0.984
Residual SS:	10.921	Std error of est:	0.801
Durbin-Watson:	2.155		

Variable	Estimated Coefficient	Standard Error	t-ratio	Prob > t
CONST	1.79721773	1.24020347	1.449	0.1655
X	0.40049188	0.03535863	11.327	0.0000
XLAG	0.18129101	0.03796536	4.775	0.0002
TREND	0.14967412	0.03104828	4.821	0.0002

## Chapter 4

# Linear Regression Reference

A summary table listing all the procedures is displayed below.

<i>Procedure</i>	<i>Description</i>	<i>Page</i>
<b>L2SLS</b>	Linear Two-stage Least Squares Estimation	44
<b>L3SLS</b>	Linear Three-stage Least Squares Estimation	49
<b>LREG</b>	Ordinary Least Squares Estimation	55
<b>LRERROR</b>	Error Handling Procedure	64
<b>LRFETCH</b>	Extracts Important Statistics	66
<b>LRSET</b>	Resets All Global Variables	68
<b>LRTEST</b>	Performs Linear Hypothesis Testing	69
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<b>RMATRIX</b>	Constructs Restriction Matrix	80
<b>SRMATRIX</b>	Constructs System Restriction Matrix	82

---

# L2SLS

---

L2SLS (Linear Two-Stage Least Squares) is a single equation technique which employs the generalized least squares rules for estimating equations in a simultaneous equations model.

## ■ Library

LR

## ■ Format

$Q = \text{L2SLS}(\text{dataset}, \text{LHS\_var}, \text{RHS\_vars}, \text{EXO\_vars}, \text{Restrict});$

## ■ Input

*dataset*      string, name of **GAUSS** data set.

*LHS\_var*      character, name of the endogenous variable in the equation.

*RHS\_vars*    character vector of all the right-hand side variables in the equation. If a constant vector is desired, simply put "CONST" in the *RHS\_vars* list.

*EXO\_vars*    character vector of all exogenous variables in the system. Specify "CONST" in the *EXO\_vars* list should a constant vector be desired.

*Restrict*     string or 0, if *Restrict* equals 0, estimation without restrictions is performed. Otherwise, the estimator is estimated with the given restrictions. The syntax of *Restrict* is as follows:

$\text{Restrict} = \text{"restriction1, restriction2, } \dots, \text{restrictionJ"};$

More than one restriction is allowed provided each is separated by a comma. Each restriction must be written as a linear equation with all variables in the left hand side and the constant in the right hand side (i.e.,  $x1 + x2 = 1$ ). Variables shown in each restriction must be variables in the right-hand side of the equation. Restrictions in the *Restrict* argument must be consistent and not redundant otherwise error messages occur. *You should make sure that only the parameters associated with the variables are restricted, and not the variables in the model themselves.*

Example:

```
restrict = "plag - p = 0";
```



## ■ Output

$Q$  vector, a *packed* output vector which contains all calculated statistics. Details of the statistics are given as below:

<i>Var. name</i>	<i>Description</i>
model	name of the estimation procedure
nms	name of the regressors
b	regression coefficients
vc	variance-covariance matrix of the coefficients
se	standard errors of the coefficients
s2	variance of the estimate ( $\hat{\sigma}^2$ )
cx	correlation matrix of the coefficients
rsq	$R^2$
rbsq	adjusted $R^2$
dw	Durbin-Watson statistic
sse	residual sum of square
nobs	number of observations
ixtx	$(X'X)^{-1}$ matrix as defined in equation (1)
xtz	$X'Z_j$ matrix as defined in equation (1)
xyt	$X'Y_j$ vector as defined in equation (1)

Note that the output vector is a *packed* vector and can not be viewed directly. For your convenience, **LRFETCH** provides a method for the extraction of the following statistics: nms, b, vc, se, s2, cx, rsq, dw, nobs, and sse. For example:

```
{ nms,b,vc,se,s2,cx,rsq,dw,nobs,sse } = lrfetch(Q);
```

or

```
{ nms,b,vc,se,s2,cx,rsq,dw,nobs,sse }  
= lrfetch(l2sls(dataset,l_var,r_vars,e_vars,0));
```

Note that the **LRFETCH** does not extract everything inside the output vector and the variables are not called by their name. Alternatively use the **VLIST** and **VREAD** functions. **VLIST** reveals the contents of the output vector and **VREAD** extracts variables by their name.

Example:

```
vlist(Q);          /* LISTS THE CONTENTS OF Q. */  
b = vread(Q,"b");   /* EXTRACTS b FROM Q. */  
sse = vread(Q,"sse"); /* EXTRACTS sse FROM Q. */
```

If errors are encountered, it is handled with the low order bit of the trap flag.

**TRAP 0** terminate with error message

**TRAP 1** return scalar error code in  $Q$

For more details of the **TRAP**, see the command reference of the **GAUSS** manual. Since the returning error code appears as a missing value, it can be translated with the command `scalerr(Q)` or be viewed with the **LRERROR** procedure. See the **LRERROR** procedure for more details. Definitions of the error codes can be found in Section 2.6.2 of this manual.

## ■ Globals

**\_lrdv** scalar, determines which divisor is used to compute  $\hat{\sigma}_{jj}$ .

**0**  $(T - K)$  is used as divisor, where  $T$  is the number of observations,  $K$  is the number of all right-hand side variables in the equation.

**1**  $T$  is used as divisor - this provides good asymptotic properties for the estimator when the sample size is large.

Default = 1.

**\_lrpcor** scalar, if 1, print the correlation matrix of coefficients. This is the  $\left[ Z_j' X (X' X)^{-1} X' Z_j \right]^{-1}$  matrix scaled to unit diagonals and is *not* the correlation matrix of variables. Default = 0.

**\_lrpcov** scalar, if 1, print the covariance matrix of coefficients which is  $\hat{\sigma}_{jj} \left[ Z_j' X (X' X)^{-1} X' Z_j \right]^{-1}$ , where  $\hat{\sigma}_{jj}$  is the mean squared error. Default = 0.

**\_\_\_output** scalar, determines printing of intermediate results.

**0** nothing is written.

**1** serial ASCII output format suitable for disk files or printers.

Default = 1.

**\_\_\_range** 2×1 vector, specifies the range of the data set to be used in estimation. The first element specifies the beginning observation while the second element specifies the ending observation. For example: **\_\_\_range**={ 100,200 }. Default is { 0,0 } and uses the whole data set.

**\_\_\_title** string, message printed at the top of the results. Default = "".

## ■ Remarks

**L2SLS** is applicable to equations which are overidentified or exactly identified. Note that L2SLS provides identical estimates as those of the Indirect Least Squares (ILS) when equations are just identified. However, for an overidentified equation, the ILS can not be used. Instead, the usual alternative is the Two-Stage Least Squares. Good references can be found in Judge, Hill, Griffiths, Lütkepohl, and Lee [8], Judge, Griffiths, Hill, Lütkepohl, and Lee [9], Greene [6], and Johnston [7].

The L2SLS estimator and its asymptotic variance are as follows:

$$\hat{\delta}_{j,l2sls} = \left[ Z_j' X (X' X)^{-1} X' Z_j \right]^{-1} \left[ Z_j' X (X' X)^{-1} X' Y_j \right] \quad (1)$$

$$AVAR(\hat{\delta}_{j,l2sls}) = \hat{\sigma}_{jj} \left[ Z_j' X (X' X)^{-1} X' Z_j \right]^{-1} \quad (2)$$

where

$$\hat{\sigma}_{jj} = \frac{(Y_j - Z_j \hat{\delta}_{j,l2sls})'(Y_j - Z_j \hat{\delta}_{j,l2sls})}{T} \quad (3)$$

and  $X$  is the matrix of all exogenous variables in the system,  $Y_j$  and  $Z_j$  are the endogenous variable and the right-hand side variables respectively in the  $j^{th}$  equation, and  $T$  is the total number of observations.

Note:

1. You must be able to specify which variables are endogenous and which are exogenous.
2.  $\hat{\delta}_{j,l2sls}$  can be viewed as an instrumental variables estimator with the set of instruments  $(X(X'X)^{-1}X'Z_j)$ .
3. The denominator in calculating the  $\hat{\sigma}_{jj}$  is  $T$  and it provides good asymptotic properties for the estimator. In case of small samples, you may choose  $T - K_j$  as the divisor, where  $K_j$  is the number of right-hand side variables in the  $j^{th}$  equation, instead of  $T$ . This is accomplished by changing the global variable **\_lrdv** to 0.
4. Linear hypothesis testing can be tested with the **LRTEST** procedure. However, the distribution is unknown and the test statistic can only be viewed as being asymptotically Chi-Square.
5. Linear a priori restrictions can be imposed on the estimated coefficients.

6.  $R^2$  calculated here is not well defined and could be negative.

Missing data are handled automatically. That is, any observation which has a missing value on any variable is removed from computation.

## ■ Example

The following example is from Judge, Hill, Griffiths, Lütkepohl, and Lee [8, page 656].

```

/*****
Program file: lr11.e
Data set:      t15_1
*****/

library lr;
lrset;
output file = lr11.out reset;

dataset = "t15_1";

_lrdv = 0;
x = { x1,x2,x3,x4,x5 };

y = { y1 };                      /* FIRST EQUATION */
z = { x1,y2,y3 };
call l2sls(dataset,y,z,x,0);

y = { y2 };                      /* SECOND EQUATION */
z = { x1,y1,x2,x3,x4 };
call l2sls(dataset,y,z,x,0);

y = { y3 };                      /* THIRD EQUATION */
z = { x1,y2,x2,x5 };
call l2sls(dataset,y,z,x,0);

output off;

/***** end of program file *****/

```

## ■ Source

l2sls.src

---

# L3SLS

---

L3SLS (Linear Three-Stage Least Squares) is a procedure for the estimation of the parameters of a system of simultaneous equations. A synopsis of the estimation procedure is found in Judge, Hill, Griffiths, Lütkepohl, and Lee [8, Ch. 15], Greene [6, Ch. 19], and Johnston [7, Ch. 11].

## ■ Library

LR

## ■ Format

$Q = \text{L3SLS}(\text{dataset}, \text{LHS\_vars}, \text{RHS\_vars}, \text{EXO\_vars}, \text{Novars}, \text{Restrict});$

## ■ Input

*dataset* string, name of **GAUSS** data set.

*LHS\_vars* character vector of the endogenous variables in the model.

*RHS\_vars* character vector of all right-hand side variable names in the systems. The order of the variable names must correspond to the order of the equations when they are stacked. For example:

```
X_vars = { const, x1, x2, ..., xk,    /* equation 1 */
           const, y1, x1, ..., xn,    /* equation 2 */
           :
           :
           const, y6, x2, ..., xk }; /* equation M */
```

If a constant vector is desired for one particular equation, simply put “CONST” in the *RHS\_vars* list.

*EXO\_vars* character vector of all exogenous variables in the system. Specify “CONST” in the *EXO\_vars* list should a constant vector be desired.

*Novars* numeric vector to determine the number of right hand side variables in each equation. For example:

```
Novars = { 3, 4, 5 };
```

From the above, there are 3 right-hand side variables in the 1<sup>st</sup> equation, 4 variables in the 2<sup>nd</sup> equation, and 5 variables in the last equation.

*Restrict* string or 0, if *restrict* equals 0, estimation without restrictions is performed. Otherwise, the estimator is estimated with the given restrictions. The syntax for the *Restrict* is as follows:

*Restrict* = "restriction1, restriction2, ..., restrictionJ";

More than one restriction is allowed provided each is separated by a comma. Each restriction must be written as a linear equation with all variables in the left hand side and the constant in the right hand side (i.e.,  $x1 : 1 + x1 : 2 = 1$ ). Variables shown in each restriction must be variables in the regression model. Note that the numeric value following the colon (:) signifies which equation the variable comes from (i.e., 3X4:10 indicates the X4 variable comes from the 10<sup>th</sup> equation). Restrictions in the *Restrict* argument must be consistent and not redundant otherwise error messages occur. *Note that only the parameters associated with the variables are restricted, and not the variables in the model.* For example:

```
restrict = "const:1 + const:2 + const:3 = 1,
           trend:1 = 0, trend:2 = 0, trend:3 = 0";
```

## ■ Output

*Q* vector, a *packed* output vector which contains all calculated statistics. Details of the statistics are given as below:

<i>Var. name</i>	<i>Description</i>
model	name of the estimation procedure
nms	name of the regressors
b	regression coefficients
vc	variance-covariance matrix of the coefficients
se	standard errors of the coefficients
s2	variance of the estimate ( $\hat{\sigma}^2$ )
cx	correlation matrix of the coefficients
rsq	$R^2$
rbsq	adjusted $R^2$
dw	Durbin-Watson statistic
sse	residual sum of square
nobs	number of observations
ixtx	$(X'X)^{-1}$ of the $\left[ Z'(\hat{\Sigma}^{-1} \otimes X(X'X)^{-1}X')Z \right]^{-1}$
sigma	residual covariance matrix $\hat{\Sigma}$
novars	no. of R.H.S. variables in each equation

*Note that the output vector is a packed vector and can not be viewed directly.* For your convenience, **LRFETCH** provides for the extraction of the following statistics: nms, b, vc, se, s2, cx, rsq, dw, nobs, and sse. For example:

```
{ nms,b,vc,se,s2,cx,rsq,dw,nobs,sse } = lrfetch(Q);
      or
{ nms,b,vc,se,s2,cx,rsq,dw,nobs,sse }
  = lrfetch(l3sls(data,L_var,R_vars,E_vars,No_vars,0));
```

Note that the **LRFETCH** does not extract everything inside the output vector and variables are not called by their name. Alternatively use the **VLIST** and **VREAD** functions. **VLIST** reveals the contents of the output vector and **VREAD** extracts variables by their name. For example:

```
vlist(Q);           /* LISTS THE CONTENTS OF Q. */
b = vread(Q,"b");    /* EXTRACTS THE b FROM Q. */
sigma = vread(Q,"sigma"); /* EXTRACTS THE sigma. */
```

If errors are encountered, it is handled with the low order bit of the trap flag.

**TRAP 0** terminate with error message

**TRAP 1** return scalar error code in  $Q$

For more details of the **TRAP**, see the command reference of the **GAUSS** manual. Since the returning error code appears as a missing value, it can be translated with the command `scalerr(Q)` or be viewed with the **LRERROR** procedure. See the **LRERROR** procedure for more details. Definitions of the error codes can be found in Section 2.6.2 of this manual.

## ■ Globals

- \_\_lrdv** scalar, determines which divisor is used to compute  $\hat{\sigma}_{ij}$ .
- 0**  $(MT - K)/M$  is used as divisor, where  $M$  is the number of equations,  $T$  is the of observations, and  $K$  is the number of all estimated parameters in the model.
  - 1**  $T$  is used as divisor and would provide good asymptotic properties for the estimator when sample size is large.
- Default = 1.
- \_\_lriter** scalar, sets the maximum number of iterations for the *iterative three-stage least squares regression*. The iterative process is also subject to the convergence criterion **\_\_lrtol**.
- Default = 1.
- \_\_lresult** scalar.

- 1 print only Three-stage results.
- 2 print both Two-stage and Three-stage results.

Default = 2.

**\_\_lrpcor** scalar, if 1, print the correlation matrix of all coefficients in the system after convergence.  
This is the  $\left[ Z'(\hat{\Sigma}^{-1} \otimes X(X'X)^{-1}X')Z \right]^{-1}$  matrix scaled to unit diagonals and is *not* the correlation matrix of variables.  
Default = 0.

**\_\_lrcov** scalar, if 1, print the covariance matrix of all coefficients in the system after convergence which is  $\left[ Z'(\hat{\Sigma}^{-1} \otimes X(X'X)^{-1}X')Z \right]^{-1}$ . Default = 0.

**\_\_lrtol** scalar, specifies a convergence criterion to stop the iterative process. The iterative process continues until either the iteration limit specified in **\_\_lriter** is reached or the percentage change in the log of determinant of  $\hat{\Sigma}$  is less than the convergence criterion. Mathematically, the convergence criterion is written as follows:

$$ABS \left[ (\log \hat{\Sigma}_{current} - \log \hat{\Sigma}_{previous}) / \log \hat{\Sigma}_{previous} \right] \times 100 \leq lrtol$$

Default = 0.0001.

**\_\_\_output** scalar, determines printing of intermediate results.

- 0 nothing is written.
- 1 serial ASCII output format suitable for disk files or printers.

Default = 1.

**\_\_\_range** 2×1 vector, specifies the range of the data set to be used in estimation. The first element specifies the beginning observation while the second element specifies the ending observation. For example: **\_\_\_range**={ 100,200 }. Default is { 0,0 } and uses the whole data set.

**\_\_\_title** string, message printed at the top of the results. Default = “”.

## ■ Remarks

The L3SLS estimator and its asymptotic variance are as follows:

$$\hat{\delta}_{j,l3sls} = \left[ Z'(\hat{\Sigma}^{-1} \otimes X(X'X)^{-1}X')Z \right]^{-1} \left[ Z'(\hat{\Sigma}^{-1} \otimes X(X'X)^{-1}X')Y \right] \quad (1)$$

$$AVAR(\hat{\delta}_{j,l3sls}) = \left[ Z'(\hat{\Sigma}^{-1} \otimes X(X'X)^{-1}X')Z \right]^{-1} \quad (2)$$



## 4. LINEAR REGRESSION REFERENCE

where  $X$ ,  $Y$  and  $Z$  are the matrix of all exogenous variables, vector of endogenous variables, and matrix of all right-hand side variables, respectively, in the systems.  $\hat{\Sigma}$  is the covariance matrix of the residuals and its elements  $\hat{\sigma}_{ij}$  are computed from the *Two-stage least squares estimator*. That is:

$$\hat{\sigma}_{ij} = \frac{(Y_i - Z_i \hat{\delta}_{i,l2s})'(Y_j - Z_j \hat{\delta}_{j,l2s})}{T} \quad (3)$$

where  $T$  is the total number of observations.

Note:

1. Before using L3SLS, you should remove all unidentified equations and all identities, since the latter have zero disturbances which would render the  $\hat{\Sigma}$  matrix singular [7, page 490].
2. Although L3SLS can perform Iterated Three-Stage Least Squares estimation, this does not guarantee a maximum likelihood estimator nor that the asymptotic efficiency will improve [6, page 633].
3. The default for the denominator in calculating the  $\hat{\sigma}_{ij}$  is  $T$ . However, by changing `_lrdv` to 0, you force the substitution of  $(MT - K)/M$  for  $T$  as the divisor, where  $M$  is the number of equations,  $T$  is the number of observations, and  $K$  is the number of all estimated parameters in the model.
4. Linear hypothesis testing can be done with the LRTEST procedure.
5. Restrictions on coefficients of different structural equations can be imposed. However, only linear restrictions are allowed.
6.  $R^2$  calculated for each equation is not well defined and could be negative.

Missing data are handled automatically. That is, any observation which has a missing value on any variable is removed from computation.

## ■ Example

This example is from Judge, Hill, Griffiths, Lütkepohl, and Lee [8, page 656].

```

/*****
Program file: lr12.e
Data set:      t15_1
*****/

library lr;
lrset;
```

```

output file = lr12.out reset;

dataset = "t15_1";
x = { const,x2,x3,x4,x5 };
y = { y1,y2,y3 };
z = { const,y2,y3,const,y1,x2,x3,x4,const,y2,x2,x5 };
novars = { 3,5,4 };

_lresult = 1;    /* PRINT ONLY THE THREE-STAGE RESULTS */
_lrdv = 1;       /* USING N AS DIVISOR */
call l3sls(dataset,y,z,x,novars,0);
output off;

/***** end of program file *****/

```

## ■ Source

l3sls.src

---

# LREG

---

**LREG** is a general procedure for linear regression. It applies the method of *Ordinary Least Squares* to perform multiple regression. References may be found in any standard textbook of statistics or econometrics.

## ■ Library

LR

## ■ Format

$Q = \text{LREG}(\text{dataset}, \text{depvar}, \text{indvars}, \text{Restrict});$

## ■ Input

*dataset*      string, name of **GAUSS** data set.

*depvar*      character, name of the dependent variable.

*indvars*      character vector of all independent variable names. If a constant vector is desired, simply put "CONST" in the *indvars* list.

*Restrict*      string or 0, if *Restrict* equals 0, estimation without restrictions is performed. Otherwise, the *Restricted Least Squares* is done with the given restrictions. The syntax of *Restrict* is as follows:

*Restrict* = "restriction1, restriction2, ..., restrictionJ";

More than one restriction is allowed provided each is separated by a comma. Each restriction must be written as a linear equation with all variables in the left hand side and the constant in the right hand side (i.e., *restrict* = " $x_1 + x_2 = 1, x_3 - x_4 = 0$ "). Variables shown in each restriction must be variables in the right-hand side of the equation. Restrictions in the *Restrict* argument must be consistent and not redundant otherwise error messages occur. *Note that only the parameters associated with the variables are restricted, and not the variables.* For example:

```
restrict = "x11 + x22 + x33 = 1,
           x12 - x21 = 0, x23 - x32 = 0";
```

## ■ Output

$Q$  vector, a *packed* output vector which contains all calculated statistics. Details of the statistics are given as below:

<i>Var. name</i>	<i>Description</i>
model	name of the estimation procedure
nms	name of the regressors
b	regression coefficients
vc	variance-covariance matrix of the coefficients
se	standard errors of the coefficients
s2	variance of the estimate ( $\hat{\sigma}^2$ )
cx	correlation matrix of the coefficients
rsq	$R^2$
rbsq	adjusted $R^2$
dw	Durbin-Watson statistic
sse	residual sum of square
nobs	number of observations
xtx	moment matrix of $X$ , (i.e., $X'X$ )
xy	the $X'Y$ matrix

*Note that the output vector is a packed vector and cannot be viewed directly.* For your convenience, **LRFETCH** provides for the extraction of the following statistics: nms, b, vc, se, s2, cx, rsq, dw, nobs, and sse. For example:

```
{ nms,b,vc,se,s2,cx,rsq,dw,nobs,sse } = lrfetch(Q);
```

or

```
{ nms,b,vc,se,s2,cx,rsq,dw,nobs,sse }  
  = lrfetch(lreg(dataset,dv,iv,0));
```

**LRFETCH** does not extract everything inside the output vector and variables are not called by their name. Alternatively, to get information from the output vector use the **VLIST** and **VREAD** functions. **VLIST** reveals the contents of the output vector and **VREAD** extracts variables by their name. For example:

```
vlist(Q);           /* LIST THE CONTENTS OF Q.*/  
b = vread(Q,"b");   /* EXTRACTS BOTH b AND s2. */  
s2 = vread(Q,"s2");
```

If errors are encountered, it is handled with the low order bit of the trap flag.

**TRAP 0** terminate with error message

**TRAP 1** return scalar error code in  $Q$

For more details of the **TRAP**, see the command reference of the **GAUSS** manual. Since the returning error code appears as a missing value, it can be translated with the command `scalerr(Q)` or be viewed with the **LRERROR** procedure. See the **LRERROR** procedure for more details. Definitions of the error codes can be found in Section 2.6.2 of this manual.

## ■ Globals

- \_lregcol** scalar, if 1, perform collinearity diagnostics. Statistics calculated are described as above. Default = 0.
- \_lreghc** scalar, if 1, the heteroskedastic-consistent covariance matrix estimator is calculated. Default = 0.
- \_lregres** string, a file name to request influence diagnostics. Statistics generated from the diagnostics are saved under this file name. Besides the diagnostic statistics, the predicted values, dependent variable and independent variables are also saved. They are saved in the following order:

Col. #	Name	Description
1	RES	Residuals = (observed-predicted)
2	HAT	Hat Matrix Values
3	SRES	Standardized Residuals
4	RSTUDENT	Studentized Residuals
5	COOK	Cook Influence Statistics
6	YHAT	Predicted Values
7	<i>depname</i>	Dependent Variable
8 +	<i>indname</i>	Independent Variables

- \_lrpcor** scalar, if 1, print the correlation matrix of coefficients. This is the  $(X'X)^{-1}$  matrix scaled to unit diagonals and is *not* the correlation matrix of variables. Default = 0.
- \_lrpcov** scalar, if 1, print the covariance matrix of coefficients which is  $\hat{\sigma}^2(X'X)^{-1}$ , where  $\hat{\sigma}^2$  is the mean squared error. Default = 0.
- \_\_\_output** scalar, determines printing of intermediate results.
- 0** nothing is written.
- 1** serial ASCII output format suitable for disk files or printers.
- Default = 1.

- \_\_\_range** 2×1 vector, specifies the range of the data set to be used in estimation. The first element specifies the beginning observation while the second element specifies the ending observation. For example: **\_\_\_range**={ 100,200 }. Default is { 0,0 } and uses the whole data set.
- \_\_\_title** string, message printed at the top of the results. Default = “”.
- \_\_\_weight** string, name of the weight variable or scalar, column number of weight variable. By default, unweighted least squares is calculated.

## ■ Remarks

Some features of **LREG**:

- estimates parameters subject to linear constraints.
- performs *Weighted Least Squares*.
- calculates *Heteroskedastic-consistent Standard Errors*.
- performs both influence and collinearity diagnostics.

The *Ordinary Least Squares* estimator and its variances are as follows:

$$b_{ols} = (X'X)^{-1}X'Y$$

$$Var(b_{ols}) = \hat{\sigma}^2(X'X)^{-1}$$

where  $\hat{\sigma}^2 = (Y - Xb)'(Y - Xb)/(T - K)$  and  $Y$  is the dependent variable,  $X$  is a list of independent variables.  $T$  and  $K$  are respectively the total number of observations and total number of estimated coefficients.

For estimated parameters subject to linear constraints, the restricted estimator and its variances are as follows:

$$b^* = b - (X'X)^{-1}R' [R(X'X)^{-1}R']^{-1}(Rb - z)$$

$$Var(b^*) = \hat{\sigma}^2 \left[ (X'X)^{-1} - (X'X)^{-1}R' [R(X'X)^{-1}R']^{-1}R(X'X)^{-1} \right]$$

where  $R$  and  $z$  are the restriction matrix and vector respectively. Both  $\hat{\sigma}^2$  and  $X$  are already defined as above.

### Weighted Least Squares

When the error variances are not equal, ordinary least squares estimation are unbiased and consistent, *but not efficient*, (i.e., they are not the minimum variance estimates). Let the matrix  $W$  be a diagonal matrix containing the weights  $w_i$ , and if the weights are inversely proportional to the error variances (i.e.,  $Var(e_i) = \sigma^2/w_i$ ).

The *Weighted Least Squares* estimators are:

$$b_{wls} = (X'WX)^{-1}X'WY$$

Note that if  $W = I$ , as it would be for unweighted least squares,  $b_{wls} = b_{ols}$ . Weighted least squares is a special case of the generalized least squares. In calculating the weighted least squares estimator, the weights are chosen to be greater than zero and normalized to sum to the number of observations. *To perform the weighted least squares estimation, you must assign the name or column number of a weight variable to the global variable `___weight`.*

### Heteroskedastic-consistent Standard Errors

White [16] has demonstrated that in the absence of precise knowledge of the form of heteroskedasticity, it is still possible to obtain a consistent estimator of the covariance matrix of  $b$ . This *heteroskedasticity-consistent covariance matrix estimator* is defined as:

$$HC \ Var(b) = (X'X)^{-1}X'\hat{\Lambda}X(X'X)^{-1}$$

where  $\hat{\Lambda}$  is a diagonal matrix holding all the squares of the errors (i.e.,  $diag(\hat{e}_1^2, \hat{e}_2^2, \dots, \hat{e}_T^2)$ ). This estimator is extremely useful since the precise nature of the heteroskedasticity is not known most of the time. *In order to calculate the  $HC \ Var(b)$ , you must set `___lreghc` = 1.*

### Influence Diagnostics

Influence diagnostics would provide the following statistics: hat or leverage values, standardized and studentized residuals, and Cook's distance measure. Let  $X_i$  and  $Y_i$  be the  $i^{th}$  observation of the  $X$  matrix and  $Y$  vector respectively,  $e_i$  be the  $i^{th}$  residual (i.e.,  $e_i = Y_i - X_i b$ ) and  $\hat{\sigma}_{-i}^2$  be the variance estimate of  $\sigma^2$  without the  $i^{th}$  observation and  $b_{-i}$  be the least squares estimates after removing the  $i^{th}$  observation.

**Hat or leverage values** ( $h_i$ ) is defined as follows:

$$h_i = X_i(X'X)^{-1}X_i'$$

$h_i$  is a measure of how far the  $i^{th}$  observation is from the center of the data in terms of the  $X$  values. Thus, a large leverage value  $h_i$  indicates that the  $i^{th}$  observation is distant from the center of the  $X$  observations.

**Standardized residuals:** It can be shown that

$$Var(e_i) = \sigma^2(1 - h_i)$$

An unbiased estimator of this variance is:

$$Var(e_i) = \hat{\sigma}^2(1 - h_i)$$

The ratio of  $e_i$  to  $\sqrt{Var(e_i)}$  is called the standardized residual ( $r_i$ ):

$$r_i = \frac{e_i}{\hat{\sigma}\sqrt{1 - h_i}}$$

Note that the residuals  $e_i$  have substantially different sampling variations if the leverage values  $h_i$  differ significantly. Hence, the advantage of  $r_i$  is that it has constant variance when the model is correct. Weisberg [15] refers to this as the internally studentized residual.

**Studentized residuals** ( $r_{-i}$ ) are defined:

$$r_{-i} = r_i \sqrt{\frac{\hat{\sigma}^2}{\hat{\sigma}_{-i}^2}}$$

The advantage of the studentized residual can be seen when the  $i^{th}$  observation is far from the center of the data. If the  $i^{th}$  observation is removed,  $\hat{\sigma}_{-i}^2$  is smaller, which makes the studentized residual larger relative to the standardized residual.

**Cook's distance measure** ( $D_i$ ) measures the change in the estimated coefficients when the  $i^{th}$  observation is removed from the regression. The larger the value of  $D_i$ , the greater is the change in the estimates.

$$D_i = \frac{(b_{-i} - b)'(X'X)(b_{-i} - b)}{(K - 1)\hat{\sigma}^2}$$

You must specify an output file name in the global variable `_lregres` when requesting the influence diagnostics (i.e., `_lregres="filename"`).



**Collinearity Diagnostics**

There are a variety of ways in which to detect the presence of collinearity or multicollinearity. The following statistics or measures are provided:

- determinant of the correlation matrix of the regressors
- Theil's multicollinearity effect
- variance inflation factor and its tolerance
- eigenvalue of  $X'X$
- condition number and proportion of variance of the estimate

See Judge, Hill, Griffiths, Lütkepohl, and Lee [8] for more details.

**Determinant of the correlation matrix of the regressors:** let  $|R_{xx}|$  be the determinant of the correlation matrix of the independent variables. The value of the determinant declines with increasing collinearity. Its value ranges from 0 to 1. If the independent variables are orthogonal, the value is 1, whereas with perfect collinearity among the regressors, the value is zero.

**Theil's multicollinearity effect ( $m$ ):** this measure has been suggested by Theil [14]. It is defined:

$$m = \sum_h (R^2 - R_h^2)$$

where  $R^2$  is the coefficient of determination when all of the variables are included in the regression and  $R_h^2$  is the coefficient of determination when the  $X_h$  is excluded from the independent variable list.  $R^2 - R_h^2$  is the incremental contribution due to  $X_h$ . If all the regressors are orthogonal,  $m$  would be the same as  $R^2$ . Deviations from  $R^2$  would indicate multicollinearity.

**Variance Inflation Factor ( $VIF$ ) and Tolerances ( $TOL$ ):**  $VIF$  measures the degree to which the variances of the estimated regression coefficients are inflated over linearly independent variables. The  $TOL$  is the reciprocal of the  $VIF$  (i.e.,  $TOL = 1/VIF$ ) and is compared with a tolerance limit (frequently used are 0.01, 0.001, or 0.0001), below which the variable is not entered into the model.

The  $VIF$  for the  $j^{th}$  variable is defined as:

$$VIF_j = \frac{1}{(1 - R_j^2)}$$

where  $R_j^2$  is the coefficient of multiple determination when  $X_j$  is regressed on all of the remaining independent variables. For example: if there were four independent variables,  $R_3^2$  would be the coefficient of determination from regressing  $X_3$  on  $X_1$ ,  $X_2$ , and  $X_4$ .

The largest  $VIF_j$  among all  $X$  variables is often used as an indicator of the severity of multicollinearity. A maximum  $VIF_j$  in excess of 10 would indicate multicollinearity unduly influencing the least squares estimates. Note that if all variables are orthogonal to each other, both  $VIF$  and  $TOL$  are 1.

**Eigenvalues and Condition Number:** The eigenvalues are computed from the  $X'X$  matrix. If one or more columns of  $X$  are linearly dependent, one or more of the eigenvalues is zero. When one or more columns are *nearly* linearly dependent, the ratio of the largest to the smallest eigenvalue is very large. The square root of this ratio is called the *condition number* ( $CN$ ):

$$CN = \sqrt{\frac{\lambda_{max}}{\lambda_{min}}}$$

where  $\lambda_{max}$  and  $\lambda_{min}$  denote the maximum and minimum eigenvalues of  $X'X$ , respectively. Since the eigenvalues are dependent on the scaling of the data, it would be better to normalize the data (i.e.,  $S(X'X)S$ , where  $S$  is a diagonal matrix with  $1/\sqrt{x_i'x_i}$  on the diagonals). If the regressors are orthogonal,  $CN$  is 1. Belsley, Kuh, and Welsch [1] suggest that the value of  $CN$  in excess of 30 would indicate serious problems of collinearity.

For each variable, **LREG** prints both eigenvalues and a condition number along with the variance proportion of the estimates. Coefficients with proportions in excess of 0.5 may be regarded as seriously affected by the collinearity in the  $X$  matrix.

*Note: For collinearity diagnostics, you must specify `_lregcol=1`.*

Missing data are handled automatically. That is, any observation which has a missing value on any variable is removed from computation.

## ■ Example

This example is from Judge, Hill, Griffiths, Lütkepohl, and Lee [8, page 871].

```

/*****
Program file: lr13.e
Data set:      t21_1
*****/

library lr;

```

```
lrset;
output file = lr13.out reset;

dataset = "t21_1";
y={ c };
x={ const,w,p,a };

_lregcol=1;  /* REQUEST COLLINEARITY DIAGNOSTICS */

call lreg(dataset,y,x,0);

output off;

/*+++++ end of program file ++++++*/
```

## ■ Source

lreg.src

---

# LRERROR

---

A procedure which provides interpretation of the error code returned from the procedures. You may add comments in addition to the printed error message. *In order to use this procedure, you must set the trap flag by putting **TRAP 1** in the command file.*

## ■ Library

LR

## ■ Format

LRERROR(*comment*,*errcode*);

## ■ Input

*comment*    string, user defined comment.

*errcode*    a scalar error code which is returned by the procedures.

## ■ Globals

**\_\_output**   scalar, determines printing of intermediate results.

**0**    nothing is written.

**1**    serial ASCII output format suitable for disk files or printers.

Default = 1.

## ■ Example

In this example, a user tries to trap the errors himself with the use of **TRAP**, **SCALERR**, and **LRERROR**.

```

/*****
Program file: testerr2.e
Data set:     t15_1
*****/

library lr;

```

```

lrset;
output file = testerr2.out reset;

trap 1;                                /* INITIALIZE THE TRAP */
_lrdv = 0;
x = { xx1,x2,x3,x4,x5 };               /* USER MISTYPED THE X1 */

y = { y1 };                            /* FIRST EQUATION */
z = { x1,y2,y3 };
Q = l2sls("t15_1",y,z,x,0);
if scalerr(Q);
    lrerror("Error appears in the 1st equation",Q);
    pause(3);
endif;

y = { y2 };                            /* SECOND EQUATION */
z = { x1,y1,x2,x3,x4 };
Q = l2sls("t15_1",y,z,x,0);
if scalerr(Q);
    lrerror("Error appears in the 2nd equation",Q);
    pause(3);
endif;

y = { y3 };                            /* THIRD EQUATION */
z = { x1,y2,x2,x5 };
Q = l2sls("t15_1",y,z,x,0);
if scalerr(Q);
    lrerror("Error appears in the 3rd equation",Q);
    pause(3);
endif;

trap 0 ;                               /* RESET THE TRAP */
output off;

/***** end of program file *****/

```

## ■ Source

lrutil.src

---

# LRFETCH

---

This procedure extracts important statistics from the regression output vector. Not all information is fetched. Its purpose is to provide convenient usage. For details on viewing and extracting the output vector consult the **VLIST** and **VREAD** library functions.

## ■ Library

LR

## ■ Format

$\{ nms, b, vc, se, s2, cx, rsq, dw, sse, nobs \} = \text{LRFETCH}(Q);$

## ■ Input

$Q$  results vector generated from the corresponding regression procedure.

## ■ Output

$nms$	name of the regressors.
$b$	vector of the regression coefficients.
$vc$	variance-covariance matrix of the coefficients.
$se$	standard errors of the coefficients.
$s2$	variance of the estimate $\hat{\sigma}^2$ .
$cx$	correlation matrix of the coefficients.
$rsq$	$R^2$ .
$dw$	Durbin-Watson Statistic.
$sse$	residual sum of squares.
$nobs$	number of observations analyzed.

## ■ Remarks

The size of each particular return argument depends on the regression model. For example, if one estimates a system of five equations with the **LSUR** procedure, *rsq* is a  $5 \times 1$  vector containing the  $R^2$  for each equation. A summary table listing the size of  $Q$  is displayed below.

### VARIABLE NAME

	“L2SLS”	“L3SLS”	“LREG”	“LSUR”
<i>model*</i>				
<i>nms</i>	$k \times 1$	$k \times 1$	$k \times 1$	$k \times 1$
<i>b</i>	$k \times 1$	$k \times 1$	$k \times 1$	$k \times 1$
<i>vc</i>	$k \times k$	$k \times k$	$k \times k$	$k \times k$
<i>se</i>	$k \times 1$	$k \times 1$	$k \times 1$	$k \times 1$
<i>s2</i>	<i>scalar</i>	$m \times 1$	<i>scalar</i>	$m \times 1$
<i>cx</i>	$k \times k$	$k \times k$	$k \times k$	$k \times k$
<i>rsq</i>	<i>scalar</i>	$m \times 1$	<i>scalar</i>	$m \times 1$
<i>dw</i>	<i>scalar</i>	$m \times 1$	<i>scalar</i>	$m \times 1$
<i>sse</i>	<i>scalar</i>	$m \times 1$	<i>scalar</i>	$m \times 1$
<i>nobs</i>	<i>scalar</i>	<i>scalar</i>	<i>scalar</i>	<i>scalar</i>
<i>rbsq*</i>	<i>scalar</i>	$m \times 1$	<i>scalar</i>	$m \times 1$
<i>ixtx*</i>	$p \times p$	$p \times p$	–	–
<i>sigma*</i>	–	$m \times m$	–	$m \times m$
<i>xtx*</i>	–	–	$k \times k$	–
<i>sst*</i>	–	–	<i>scalar</i>	–
<i>xy*</i>	$p \times 1$	–	$k \times 1$	–
<i>xtz*</i>	$p \times k$	–	–	–
<i>novars*</i>	–	$m \times 1$	–	$m \times 1$

where  $k$ ,  $p$  and  $m$  are respectively the total number of regressors, total number of exogenous variables and number of equations in the model. Those variable names marked with an asterisk (\*) are not extracted with the **LRFETCH**.

## ■ Source

lrutil.src

---

# LRSET

---

Purpose of this procedure is to reset *LINEAR REGRESSION* global variables to default values.

## ■ Library

LR

## ■ Format

LRSET;

## ■ Remarks

It is generally good practice to put this instruction at the top of all command files that invoke procedures in the *LINEAR REGRESSION* module. This prevents globals from being inappropriately defined when a command file is run several times or when a command file is run after another command file is executed that calls *LINEAR REGRESSION* procedures.

LRSET calls GAUSSET.

## ■ Source

lrset.src



---

# LRTEST

---

This is a test procedure that can perform linear hypothesis testing for all estimation modules in the *Linear Regression*. For **LREG**, the hypothesis test calculates the  $F$  statistic. Whereas for **L2SLS**, **L3SLS**, and **LSUR**, the  $Wald$  statistic is calculated. References can be found in Judge, Hill, Griffiths, Lütkepohl, and Lee [8], Judge, Griffiths, Hill, Lütkepohl, and Lee [9], Greene [6], and Johnston [7].

For **LREG**, the  $F$  statistics is defined as follows:

$$F_{(J,T-K)} = \frac{(R\hat{\beta} - z)' [R(X'X)^{-1}R']^{-1} (R\hat{\beta} - z)}{J\hat{\sigma}^2}$$

where  $J$  is the set of linear restrictions,  $T$  and  $K$  are the total number of observations and coefficients, respectively.  $R$  and  $z$  are the restriction matrix and vector respectively.  $X$  is the data matrix and  $\hat{\sigma}^2$  is the estimated error variance.

For **L2SLS**, **L3SLS**, and **LSUR**, the  $Wald$  statistic is defined as:

$$\chi^2_{(J)} = (R\hat{\beta} - z')(R\hat{C}R')^{-1}(R\hat{\beta} - z)$$

where  $J$  is the set of linear restrictions,  $R$  and  $z$  are the restriction matrix and vector respectively.  $\hat{\beta}$  is the corresponding estimated coefficients and  $\hat{C}$  is the covariance matrix of  $\hat{\beta}$ .

## ■ Library

LR

## ■ Format

`stat = LRTEST(Q,test);`

## ■ Input

$Q$  results vector generated from the corresponding regression procedure.

$test$  string that contains set of linear restrictions to perform the hypothesis testing.  $test$  has the following form:

$test = "test1, test2, \dots, testJ";$

More than one *test* equation is allowed provided each is separated by a comma. Each *test* equation must be written as a linear equation with all variables in the left hand side and the constant in the right hand side. Variables shown in each equation must be variables in the regression model. Equations in the *test* argument must be consistent and not redundant otherwise error messages are issued. For a system of simultaneous equations, every variable defined in each *test* equation must have a colon (:) and a numeric value following the variable. The numeric value indicates which equation the variable comes from (i.e., 3X4:10 indicates the X4 variable comes from the 10<sup>th</sup> equation). *Note that only the parameters associated with the variables are tested, and not the variables in the model.* For example:

```
/* for models such as LREG and L2SLS */
test = "x11+x22+x33=1,x12-x21=0,x23-x32=0";

/* for models such as L3SLS and LSUR */
test = "const:1 + const:2 + const:3 = 1,
        trend:1 = 0,
        trend:2 = 0,
        trend:3 = 0";
```

## ■ Output

*stat* scalar, test statistic for the corresponding regression. If errors are encountered, it is handled with the low order bit of the trap flag.

**TRAP 0** terminate with error message

**TRAP 1** return scalar error code in *stat*

For more details of the **TRAP**, see the command reference of the **GAUSS** manual. Since the returning error code appears as a missing value, it can be translated with the command `scalerr(Q)` or be viewed with the **LRERROR** procedure. See the **LRERROR** procedure for more details. Definitions of the error codes can be found in Section 2.6.2 of this manual.

## ■ Globals

**\_\_output** scalar, determines printing of intermediate results.

**0** nothing is written.

**1** serial ASCII output format suitable for disk files or printers.

Default = 1.

## ■ Example

This example is from Judge, Hill, Griffiths, Lütkepohl, and Lee [8, page 460]. Data is already logged here.

```

/*****
Program file: lr14.e
Data set:      t11_3
*****/

library lr;
lrset;
output file = lr14.out reset;

dataset = "t11_3";
lhs = { q1,q2,q3 };
rhs = { const,p1,y,
        const,p2,y,
        const,p3,y };
novars = { 3,3,3 };      /* NO. OF RHS VARIABLES IN EACH EQN. */
test = "p1:1-p2:2=0,
        p1:1-p3:3=0";

_lrdv=0;
__output = 0;    /* OUTPUT OF THE LSUR WON'T BE PRINTED */

/* LSUR estimation without restriction imposed */
stat = lsur(dataset,lhs,rhs,novars,0);

__output = 1;    /* PRINT THE RESULT FOR LRTEST */

/* Linear hypothesis testing by using LRTEST */
call lrtest(stat,test);

output off;

/***** end of program file *****/

```

Output for the example:

```

----- LSUR: Results for Linear Hypothesis Testing -----
Wald Chi-SQ(2) statistic = 1.138      Prob. = 0.566

```

---

**■ Source**`lrtest.src`

---

# LSUR

---

**LSUR** (*Linear Seemingly Unrelated Regression*) is a procedure for estimating a system of equations. It employs the technique of joint-generalized least squares which uses the covariance matrix of residuals. Linear restrictions can be imposed on the coefficients within or across equations. Hypothesis testing for these linear restrictions can be tested with the **LRTEST** procedure.

## ■ Library

LR

## ■ Format

$Q = \text{LSUR}(\text{dataset}, \text{LHS\_vars}, \text{RHS\_vars}, \text{Novars}, \text{Restrict});$

## ■ Input

*dataset* string, name of **GAUSS** data set.

*LHS\_vars* M×1 character vector of all dependent variable names in the systems. For example:

```
lhs_vars = { y1, y2, y3, ..., yM };
```

where y1 is the dependent variable for the 1<sup>st</sup> equation, y2 for the 2<sup>nd</sup> equation, and so on.

*RHS\_vars* K×1 character vector of all independent variable names in the systems. The order of the variable names must correspond to the order of the equations when they are stacked. For example:

```
rhs_vars = { const, x11, x12, ..., x1k,    /* equation 1 */
             const, x21, x22, ..., x2k,    /* equation 2 */
             :
             :
             const, xM1, xM2, ..., xMk }; /* equation M */
```

If a constant vector is desired for one particular equation, simply put "CONST" in the *RHS\_vars* list.

*Novars* M×1 numeric vector to determine the number of right hand side variables in each equation. For example:

```
novars = { 3, 4, 5 };
```

From the above, there are 3 right hand side variables in the 1<sup>st</sup> equation, 4 variables in the 2<sup>nd</sup> equation, and 5 variables in the 3<sup>rd</sup> equation.

*Restrict* string or 0, if *restrict* equals 0, estimation without restrictions is performed. Otherwise, the estimator is estimated with the given restrictions. The syntax for *Restrict* is as follows:

*Restrict* = "restriction1, restriction2, ..., restrictionJ";

More than one restriction is allowed provided each is separated by a comma. Each restriction must be written as a linear equation with all variables in the left hand side and the constant in the right hand side (i.e.,  $x1 : 1 + x1 : 2 = 1$ ). Variables shown in each restriction must be variables in the regression model. Note that the numeric value following the colon (:) signifies which equation the variable comes from (i.e., 3X4:10 indicates the X4 variable comes from the 10<sup>th</sup> equation). Restrictions in the *Restrict* argument must be consistent and not redundant otherwise error messages are returned. *Note that only the parameters associated with the variables are restricted, and not the variables in the model.* For example, suppose one wants to estimate the following 2 equations:

$$S_{it} = \alpha_i + \sum_{j=1}^2 \alpha_{ij} \ln P_{jt} + \alpha_{iY} \ln Y_t + \gamma_i \text{trend} + \varepsilon_{it} \quad i = 1, 2$$

and would like to impose three restrictions on it. That is, ( $\alpha_1 + \alpha_2 = 1$ ) and ( $\gamma_i = 0, \forall i$ ) into the model. In doing the **LSUR**, we can write the problem as follows:

```
dataset = "temp";
lhs = { s1,s2 };
rhs = { const,lp1,lp2,ly,trend,      /* equation 1 */
        const,lp1,lp2,ly,trend };    /* equation 2 */
novars = { 5,5 };
restrict = "const:1 + const:2 = 1,
           trend:1=0,
           trend:2=0";
call lsur(dataset,lhs,rhs,novars,restrict);
```

## ■ Output

*Q* vector, a *packed* output vector which contains all calculated statistics. Details of the statistics are given as below:

<i>Var. name</i>	<i>Description</i>
model	name of the estimation procedure
nms	name of the regressors
b	regression coefficients
vc	variance-covariance matrix of the coefficients
se	standard errors of the coefficients
s2	variance of the estimate ( $\hat{\sigma}^2$ )
cx	correlation matrix of the coefficients
rsq	$R^2$
rbsq	adjusted $R^2$
dw	Durbin-Watson statistic
sse	residual sum of square
nobs	number of observations
sigma	residual covariance matrix $\hat{\Sigma}$
novars	no. of R.H.S. variables in each equation

Note that the output vector is a packed vector and cannot be viewed directly. For your convenience, **LRFETCH** provides for the extraction of the following statistics: nms, b, vc, se, s2, cx, rsq, dw, nobs, and sse. For example:

```
{ nms,b,vc,se,s2,cx,rsq,dw,nobs,sse } = lrfetch(Q);
```

or

```
{ nms,b,vc,se,s2,cx,rsq,dw,nobs,sse }  
  = lrfetch(lsur(data,lhs_var,rhs_vars,no_vars,0));
```

**LRFETCH** does not extract everything inside the output vector and variables are not called by their name. Alternatively, to get information from the output use the **VLIST** and **VREAD** functions. **VLIST** reveals the contents of the output vector and **VREAD** extracts variables by their name. Example:

```
vlist(Q);           /* LISTS THE CONTENTS OF Q. */  
b = vread(Q,"b");    /* EXTRACTS THE BETA. */  
sigma = vread(Q,"sigma"); /* EXTRACTS THE SIGMA */
```

If errors are encountered, it is handled with the low order bit of the trap flag.

**TRAP 0** terminate with error message

**TRAP 1** return scalar error code in  $Q$

For more details of the **TRAP**, see the command reference of the **GAUSS** manual. Since the returning error code appears as a missing value, it can be translated with the command `scalerr(Q)` or be viewed with the **LRERROR** procedure. See the **LRERROR** procedure for more details. Definitions of the error codes can be found in Section 2.6.2 of this manual.

## ■ Globals

- \_\_lrdv** scalar, determines which divisor is used to compute the covariance matrix of residuals.
- 0**  $T - (K/M)$  is used as divisor, where  $T$  is the number of observations,  $K$  is the number of all right hand side variables in the system, and  $M$  is the total number of equations. Hence,  $(K/M)$  is the average number of coefficients per equation.
  - 1**  $T$  is used as divisor. Users are encouraged to use this, since it provides good asymptotic properties for the estimator.
- Default = 1.
- \_\_lriter** scalar, sets the maximum number of iterations for the *iterative seemingly unrelated regression*. Default = 1.
- \_\_lrpcor** scalar, if 1, print the correlation matrix of all coefficients in the system after convergence. This is the  $\left[ X' \left( \hat{\Sigma}^{-1} \otimes I \right) X \right]^{-1}$  matrix scaled to unit diagonals and is *not* the correlation matrix of variables. Default = 0.
- \_\_lrpcov** scalar, if 1, print the covariance matrix of all coefficients in the system after convergence which is  $\left[ X' \left( \hat{\Sigma}^{-1} \otimes I \right) X \right]^{-1}$ . Default = 0.
- \_\_lrtol** scalar, specifies a convergence criterion to stop the iterative process. The iterative process continues until either the iteration limit specified in **\_\_lriter** is reached or the percentage change in the log of determinant of  $\hat{\Sigma}$  is less than the convergence criterion. Mathematically, the convergence criterion is written as follows:
- $$ABS \left[ (\log \hat{\Sigma}_{current} - \log \hat{\Sigma}_{previous}) / \log \hat{\Sigma}_{previous} \right] \times 100 \leq Jrtol$$
- Default = 0.0001.
- \_\_\_output** scalar, determines printing of intermediate results.
- 0** nothing is written.
  - 1** serial ASCII output format suitable for disk files or printers.
- Default = 1.
- \_\_\_range** 2×1 vector, specifies the range of the data set to be used in estimation. The first element specifies the beginning observation while the second element specifies the ending observation. For example: **\_\_\_range**={ 100,200 }. Default is { 0,0 } and uses the whole data set.



**\_\_title** string, message printed at the top of the results. Default = “”.

## ■ Remarks

A powerful feature in **LSUR** is that it can perform *Iterative Seemingly Unrelated Regression*. The iterative process terminates when it meets the convergence criterion. Good references can be found in Judge, Hill, Griffiths, Lütkepohl, and Lee [8, Ch. 11], Judge, Griffiths, Hill, Lütkepohl, and Lee [9, Ch. 12], Greene [6, Ch. 17], and Johnston [7, Ch. 8].

The **LSUR** estimator and variance are as follows:

$$\begin{aligned}\hat{\beta}_{sur} &= \left[ X' \left( \hat{\Sigma}^{-1} \otimes I \right) X \right]^{-1} \left[ X' \left( \hat{\Sigma}^{-1} \otimes I \right) Y \right] \\ \text{Var}(\hat{\beta}_{sur}) &= \left[ X' \left( \hat{\Sigma}^{-1} \otimes I \right) X \right]^{-1}\end{aligned}$$

where  $X$  and  $Y$  are stacked by equations.  $\hat{\Sigma}$  is the estimated covariance matrix of residuals from each equation and has elements given by

$$\hat{\sigma}_{ij} = \frac{\hat{e}_i \hat{e}_j}{T} = \frac{\sum_{t=1}^T \hat{e}_{it} \hat{e}_{jt}}{T} \quad i, j = 1, 2, \dots, M$$

where  $M$  and  $T$  stand for the number of equations and number of observations respectively.

For restrictions imposed on the coefficients, the restricted estimator and variance are as follows:

$$\begin{aligned}\hat{\beta}_{sur}^* &= \hat{\beta}_{sur} - \hat{C}R' \left( R\hat{C}R' \right)^{-1} \left( R\hat{\beta}_{sur} - r \right) \\ \text{Var}(\hat{\beta}_{sur}^*) &= \hat{C} - \hat{C}R' \left( R\hat{C}R' \right)^{-1} R\hat{C}\end{aligned}$$

where  $R$  and  $r$  are the restriction matrix and vector respectively.  $\hat{C}$  is the covariance matrix of  $\hat{\beta}_{sur}$  and has the form  $\left[ X' \left( \hat{\Sigma}^{-1} \otimes I \right) X \right]^{-1}$ .

Missing data are handled automatically. That is, any observation which has a missing value on any variable is removed from computation. In this case  $R^2$  calculated for each equation is not well defined and could be negative.

## ■ Example

This example is from Judge, Hill, Griffiths, Lütkepohl, and Lee [8, page 460]. Data is already logged here.

```

/*****
Program file: lr15.e
Data set:      t11_3
*****/

library lr;
lrset;
output file = lr15.out reset;

dataset = "t11_3";
lhs = { q1,q2,q3 };
rhs = { const,p1,y,
        const,p2,y,
        const,p3,y };
novars = { 3,3,3 }; /* NO. OF RHS VARIABLES IN EACH EQN. */
restrict = "p1:1-p2:2=0,
           p1:1-p3:3=0";

_lrdv = 0; /* USING NORMAL DIVISOR */

/* LSUR ESTIMATION WITHOUT RESTRICTION IMPOSED */
result1 = lsur(dataset,lhs,rhs,novars,0);

/* LSUR ESTIMATION WITH RESTRICTION IMPOSED */
result2 = lsur(dataset,lhs,rhs,novars,restrict);

/* RESULT1 AND RESULT2 ARE VECTORS THAT STORE ALL STATISTICS
   AND ESTIMATED COEFFICIENTS. SEE VLIST AND VREAD TO LIST
   CONTENTS OF THESE VECTORS AND EXTRACT INFORMATION FROM THEM. */

print;
print "-----";
print "Variables stored in result2 are as follows: ";
print "-----";
call vlist(result2); /* VLIST IS A FUNCTION TO LIST ALL
                     VARIABLES INSIDE THE VECTOR */

format /rd 8,4;
print;
print "-----";
print "The coeff. with restrictions imposed are as follows: ";
print "-----";
let mask[1,2] = 0 1;
let fmt[2,3] = "-*. *s " 10 8
              " *.*lf " 14 8;

```

```
answer = rhs~vread(result2,"b"); /* VREAD GETS b FROM RESULT2 */
call printfm(answer,mask,fmt);

output off;

/*++++++ end of program file +++++++*/
```

## ■ Source

lsur.src

---

# RMATRIX

---

This is a procedure that constructs the restriction matrix and the constant vector for single equation models. Both the restriction matrix and the constant vector can be used for linear hypothesis testing and restricted estimation.

## ■ Library

LR

## ■ Format

$\{ R, z \} = \text{RMATRIX}(\text{Restrict}, \text{Varnames});$

## ■ Input

*Restrict* string, the restriction equations. The syntax of *Restrict* is as follows:

*Restrict* = “*restriction1, restriction2, ..., restrictionJ*”;

More than one restriction is allowed provided each is separated by a comma. Each restriction must be written as a linear equation with all variables in the left hand side and the constant in the right hand side (i.e.,  $x_1 + x_2 = 1$ ). Variables shown in each restriction must be variables in the right-hand side of the equation. Restrictions in the *Restrict* argument must be consistent and not redundant otherwise error messages occur. *Note that the corresponding variable names are used to represent the regression parameters.*

*Varnames* character vector, the variable names of the regression parameters.

## ■ Output

*R* matrix, the restriction matrix. If errors are encountered, it is handled with the low order bit of the trap flag.

**TRAP 0** terminate with error message

**TRAP 1** return scalar error code in *R*

For more details of the **TRAP**, see the command reference of the **GAUSS** manual. Since the returning error code appears as a missing value, it can be translated with the command `scalerr(Q)` or be viewed with the **LRERROR** procedure. See the **LRERROR** procedure for more details. Definitions of the error codes can be found in Section 2.6.2 of this manual.

$z$  the constant vector.

### ■ Example

Suppose you wish to perform a *Linear Hypothesis Testing*,

$$H_0 : R\beta = z$$

where the  $R$  matrix,  $\beta$ , and  $z$  vector are as follows:

$$R = \begin{bmatrix} 0 & 1 & -3 & 0 & 0 & -6 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}, \quad \beta = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \\ \beta_5 \\ \beta_6 \end{bmatrix}, \quad \text{and} \quad r = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}$$

That is to test jointly with the following equations:

$$\begin{aligned} \beta_1 - 3\beta_2 - 6\beta_5 &= 0 \\ \beta_3 + \beta_4 &= 2 \\ \beta_0 &= 0 \end{aligned}$$

By typing the following code, you can create the  $R$  matrix and  $z$  vector easily.

```
str = "x1-3x2-6x5=0, x3+x4=2, x0=0";
varnames = { x0,x1,x2,x3,x4,x5,x6 };
{ R,z } = rmatrix(str,varnames);
```

*Note that the corresponding variable names are used to represent the parameters.*

### ■ Source

`rmatrix.src`

---

# SRMATRIX

---

This is a procedure that constructs the restriction matrix and the constant vector for systems of equations models. Both the restriction matrix and the constant vector can be used for linear hypothesis testing and restricted estimation.

## ■ Library

LR

## ■ Format

$\{ R, z \} = \text{SRMATRIX}(\text{Restrict}, \text{Varnames}, \text{Novars});$

## ■ Input

*Restrict* string, the restriction equations. The syntax of *Restrict* is as follows:

*Restrict* = “*restriction1, restriction2, ..., restrictionJ*”;

More than one restriction is allowed provided each is separated by a comma. Each restriction must be written as a linear equation with all variables in the left hand side and the constant in the right hand side (i.e.,  $x1 : 1 + x1 : 2 = 1$ ). Variables shown in each restriction must be variables in the regression model. Note that the numeric value following the colon (:) signifies which equation the variable comes from (i.e., 3X4:10 indicates the X4 variable comes from the 10<sup>th</sup> equation). Restrictions in the *Restrict* argument must be consistent and not redundant otherwise error messages occur. *Note that the corresponding variable names in the model are used to represent the regression parameters.*

*Varnames* character vector, the variable names of the regression parameters.

*Novars* numeric vector to determine the number of right hand side variables in each equation. For example:

`novars = { 3, 4, 5 };`

From the above, there are 3 right hand side variables in the 1<sup>st</sup> equation, 4 variables in the 2<sup>nd</sup> equation, and 5 variables in the 3<sup>rd</sup> equation.

## ■ Output

*R* matrix, the restriction matrix. If errors are encountered, it is handled with the low order bit of the trap flag.

**TRAP 0** terminate with error message

**TRAP 1** return scalar error code in  $R$

For more details of the **TRAP**, see the command reference of the **GAUSS** manual. Since the returning error code appears as a missing value, it can be translated with the command `scalerr(Q)` or be viewed with the **LRERROR** procedure. See the **LRERROR** procedure for more details.

Definitions of the error codes can be found in Section 2.6.2 of this manual.

$z$  the constant vector.

## ■ Example

Suppose one wants to perform a restricted estimation with the following model.

$$\begin{aligned} S_1 &= \alpha_1 + \alpha_{11} \ln P_1 + \alpha_{12} \ln P_2 + \varepsilon_1 \\ S_2 &= \alpha_2 + \alpha_{21} \ln P_1 + \alpha_{22} \ln P_2 + \varepsilon_2 \end{aligned}$$

In matrix notation, the above model is as follows:

$$\begin{bmatrix} S_1 \\ S_2 \end{bmatrix} = \begin{bmatrix} 1 & \ln P_1 & \ln P_2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & \ln P_1 & \ln P_2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_{11} \\ \alpha_{12} \\ \alpha_2 \\ \alpha_{21} \\ \alpha_{22} \end{bmatrix} + \varepsilon$$

And the restrictions are,

$$\begin{aligned} \alpha_{12} - \alpha_{21} &= 0 \\ \alpha_1 + \alpha_2 &= 1 \\ \alpha_{11} + \alpha_{12} &= 0 \\ \alpha_{21} + \alpha_{22} &= 0 \end{aligned}$$

Hence, for the restricted estimation to take place, we first have to construct the  $R$  matrix and the  $z$  vector.

$$R = \begin{bmatrix} 0 & 0 & 1 & 0 & -1 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix} \quad \text{and} \quad z = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

With the use of **SRMATRIX**, we can create the  $R$  and  $Z$  easily.

## SRMATRIX

### 4. LINEAR REGRESSION REFERENCE

```
novars = { 3,3 }; /* # OF RHS VARIABLES IN EACH EQUATION */
str = "lnp2:1 - lnp1:2 = 0,
      const:1 + const:2 = 1,
      lnp1:1 + lnp2:1 = 0,
      lnp1:2 + lnp2:2 = 0";
varnames = { const,lnp1,lnp2,const,lnp1,lnp2 };
{ R,z } = srmatrix(str,varnames,novars);
```

*Users should note that the corresponding variable names are used to represent the parameters. The numeric value following the colon (:) signifies which equation the variable comes from.*

#### ■ Source

rmatrix.src



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